

$$a) \quad l_z = 10 \text{ m} \quad \epsilon_r = 4, \quad \omega = 2\pi \cdot 10^7 \frac{1}{s}$$

$$\text{elekt. Länge: } \frac{l_z}{\lambda} = \frac{l_z f}{c} = \frac{l_z}{c_0} \sqrt{\epsilon_r} \frac{\omega}{2\pi}$$

$$= \frac{10 \text{ m}}{3 \cdot 10^8 \frac{\text{m}}{\text{s}}} \cdot 2 \cdot 10^7 \cdot \frac{1}{5} = \frac{2}{3} \approx 1$$

$$b) \quad \vec{k} = \vec{e}_z \cdot \frac{2\pi}{\lambda}$$

$$\vec{E}(p, \varphi, z) = \vec{E}_A(p, \varphi) e^{-j\vec{k} \cdot \vec{e}_z z} = \vec{E}_A(p, \varphi) e^{-j\frac{2\pi}{\lambda} z}$$

$$c) \quad = \vec{E}_A(p, \varphi) e^{-j\frac{2\pi}{c_0} \sqrt{\epsilon_r} \frac{\omega}{2\pi} z}$$

$$= \vec{E}_A(p, \varphi) \cdot e^{-j\omega \sqrt{\epsilon_r} / c_0 \cdot z}$$

$$d) \quad \Delta_{2D} \Phi(p, \varphi, z=0, t) = 0$$

$$\Rightarrow \frac{1}{\rho} \cdot \frac{\partial}{\partial \rho} \left(\rho \cdot \frac{\partial \Phi}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 \Phi}{\partial \varphi^2}$$

= 0 wg. TEM-Welle
(rotationssymmetrisch)

Ansatz $\Phi(p, \varphi, z=0, t) = \text{const}_1 + \text{const}_2 \ln(\rho) \quad h(t)$
ist Lösung der DGL

e) $\vec{E}_A(p, \varphi)$ gesucht

$$\Phi(p, \varphi, z=0, t) = \text{const}_2 \cdot \ln(\rho) h(t) + \text{const}_1$$

Es gilt bei $z=0$:

$$\Phi(\rho=r_i, \varphi, z=0, t) - \Phi(\rho=r_a, \varphi, z=0, t) = U_0 \sin \omega t$$

$$\text{Re} \{ \vec{E}_A(p, \varphi) \cdot e^{j\omega t} \} = -\nabla \Phi(p, \varphi, z=0, t)$$

$$\textcircled{*} \quad \text{const}_2 \cdot \ln\left(\frac{r_i}{r_a}\right) h(t) = U_0 \sin \omega t$$

$$\Rightarrow \text{const}_2 = \frac{U_0}{\ln \frac{r_i}{r_a}} \quad \text{und} \quad h(t) = \sin \omega t$$

$$\Rightarrow \Phi = -\frac{U_0}{\ln \frac{r_a}{r_i}} \ln(\rho) \sin \omega t$$

$$\text{Re} \{ \vec{E}_A(p, \varphi) \cdot e^{j\omega t} \} = -\frac{\partial \Phi}{\partial \rho} \vec{e}_\rho = \frac{U_0}{\ln \frac{r_a}{r_i}} \cdot \frac{1}{\rho} \cdot \vec{e}_\rho \cdot \sin \omega t$$

$$\Rightarrow \vec{E}_A(p, \varphi) = -j \frac{U_0}{\ln(r_a/r_i)} \frac{1}{\rho} \vec{e}_\rho \Rightarrow \boxed{\vec{E} = \vec{E}_A e^{-j\frac{\omega}{c_0} \sqrt{\epsilon_r} z}}$$

$$f) \quad l_z = 1 \text{ m} \Rightarrow \omega = 2\pi \cdot 10^5 \cdot \frac{1}{s}$$

$$\frac{l_z}{\lambda} = \frac{l_z}{c_0} \sqrt{\epsilon_r} \frac{\omega}{2\pi} = \frac{1 \text{ m}}{3 \cdot 10^8 \frac{\text{m}}{\text{s}}} \cdot 2 \cdot 10^5 \cdot \frac{1}{s} = \frac{2}{3} \cdot 10^{-3} \ll 1$$

$$\vec{E}(\rho, \varphi, z, t) = \operatorname{Re} \{ \vec{E} \cdot e^{j\omega t} \}$$

$$= \operatorname{Re} \left\{ -j \frac{U_0}{\ln \frac{r_a}{r_i}} \cdot \frac{1}{\rho} \cdot \vec{e}_\rho e^{-jkz + j\omega t} \right\}$$

$$= \frac{U_0}{\ln \frac{r_a}{r_i}} \cdot \frac{1}{\rho} \vec{e}_\rho \operatorname{Re} \{ -j (\cos(\omega t - kz) + j \sin(\omega t - kz)) \}$$

$$= \frac{U_0}{\ln \frac{r_a}{r_i}} \cdot \frac{1}{\rho} \vec{e}_\rho \sin(\omega t - kz)$$

$\ll 1$ da $\frac{l_z}{\lambda} \ll 1$

$$\approx \frac{U_0}{\ln \frac{r_a}{r_i}} \cdot \frac{1}{\rho} \vec{e}_\rho \sin \omega t$$

$$a) E(z) = \frac{U_0}{h} \exp(-jkz) \vec{e}_x$$

$$h = \omega \sqrt{\epsilon \mu}; U_0 \text{ reelle Konstante}$$

$$\begin{aligned} \vec{H}(z) &= \frac{1}{Z_F} (\vec{n} \times \vec{E}) = \sqrt{\frac{\epsilon}{\mu}} (\vec{n} \times \vec{E}) = \sqrt{\frac{\epsilon}{\mu}} (\vec{e}_z \times \vec{e}_x) \frac{U_0}{h} e^{-jkz} \\ &= \sqrt{\frac{\epsilon}{\mu}} \vec{e}_y \cdot \frac{U_0}{h} \cdot e^{-jkz} \end{aligned}$$

$$b) U_1^h(z) = \int_{P_1}^{P_2} E(z) d\vec{r}$$

$$U_1^h(z) = U_0 e^{-jkz}$$

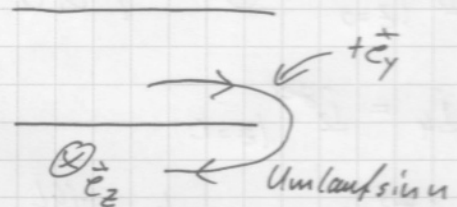
$$i_1^h(z) = ?$$

$$\text{rot } \vec{H} = \vec{J} + \vec{D}$$

$$\oint \vec{H} \cdot d\vec{s} = \vec{I} \rightarrow b \cdot H(z) = \vec{I}$$

$$\Rightarrow i_1^h(z) = b \sqrt{\frac{\epsilon}{\mu}} \frac{U_0}{h} e^{-jkz}$$

$$Z_L = \frac{U_1^h}{i_1^h} = \frac{h}{b} \sqrt{\frac{\epsilon}{\mu}}^{-1} = Z_F = \frac{h}{b}$$



$$c) \underline{z=0} \quad \underline{U_1^h} + \underline{U_1^r} = \underline{U_2^h} + \underline{U_2^r} \quad (\text{mit } U_y^x = U_y^x \cdot e^{\pm jkz}) \quad (1)$$

$$- \underline{i_1^r} + \underline{i_1^h} = \underline{i_2^h} - \underline{i_2^r} + \underline{i_R} = \underline{i_2^h} - \underline{i_2^r} + \frac{\underline{U_2^h} + \underline{U_2^r}}{R} \quad (2)$$

$$\underline{z=L}: \underline{U_2^h} \cdot e^{-jkl} = -\underline{U_2^r} \cdot e^{+jkl} \quad (3)$$

$$d) l_{\min} = \frac{\lambda}{4} \text{ und } \underline{U_1^r} = 0$$

$$\Rightarrow \underline{U_1^h} = \underline{U_2^h} + \underline{U_2^r} \quad (1)$$

$$\frac{\underline{U_1^h}}{Z_L} = \frac{\underline{U_2^h}}{Z_L} - \frac{\underline{U_2^r}}{Z_L} + \frac{\underline{U_2^h} + \underline{U_2^r}}{R} \quad (2)$$

$$\underline{U_2^h}(-j) = -\underline{U_2^r} \cdot j \Rightarrow \underline{U_2^h} = +\underline{U_2^r} \quad (3)$$

$$\underline{U_1^h} = \underline{U_2^h} + \underline{U_2^r} \Rightarrow \underline{U_1^h} = U_0 = 2 \cdot \underline{U_2^h} \quad (1) + (3)$$

$$(2) \quad \frac{\underline{U_1^h}}{Z_L} = \frac{U_0}{Z_L} = \frac{\underline{U_2^h}}{Z_L} - \frac{\underline{U_2^r}}{Z_L} + \frac{\underline{U_2^h} + \underline{U_2^r}}{R}$$

$$\Rightarrow \frac{U_0}{Z_L} = \frac{U_0^h}{Z_L} - \frac{U_0^h}{Z_L} + \frac{U_0^h + U_0^h}{R} \Rightarrow U_0 = \frac{2U_2^h}{R} Z_L$$

$$\text{mit (1) folgt: } \underline{R = Z_L}$$

$$\begin{aligned} e^{jk \frac{\lambda}{4}} &= e^{-j \frac{2\pi}{4}} = \\ \cos \frac{\pi}{2} - j \sin \left(\frac{\pi}{2} \right) &= -j \\ e^{jk \frac{\lambda}{4}} &= j \end{aligned}$$

$$\underline{H}_{x1} = \frac{\beta^2}{j\omega\mu_0} (\underline{B}_1 \sin(\underline{k}_{x1} \cdot x)) e^{-j\beta z} \quad (\underline{k}_1^2 + \frac{\partial^2}{\partial x^2}) \underline{f}_1 = \beta^2 \underline{f}_1$$

$$\underline{H}_{x1} = \frac{1}{j\omega\mu_0} \frac{\partial^2 \underline{f}_1}{\partial x \partial y} \equiv 0 \quad \text{da } \underline{f}_1(x, z)$$

$$\underline{H}_{z1} = \frac{1}{j\omega\mu_0} \frac{\partial^2 \underline{f}_1}{\partial x \partial y} = -\frac{\beta}{\omega\mu_0} \frac{\partial \underline{f}_1}{\partial x} = -\frac{\beta \underline{k}_{x1}}{\omega\mu_0} (\underline{B}_1 \cos(\underline{k}_{x1} x)) e^{-j\beta z}$$

Gebiet 2 $\underline{E}_{x2} \equiv 0 \quad \underline{E}_{z2} \equiv 0 \quad \underline{H}_{y2} \equiv 0$

$$\underline{E}_{y2} = j\beta \underline{B}_2 \sin(\underline{k}_{x2} (2h-x)) e^{-j\beta z}$$

$$\underline{H}_{x2} = \frac{\beta^2}{j\omega\mu_0} \underline{B}_2 \sin(\underline{k}_{x2} (2h-x)) e^{-j\beta z}$$

$$\underline{H}_{z2} = -\frac{\beta \underline{k}_{x2}}{\omega\mu_0} (-\underline{B}_2 \cos(\underline{k}_{x2} (2h-x))) e^{-j\beta z}$$

c) Stetigkeit bei $x=h$: $\vec{E}_{\tan 1} = \vec{E}_{\tan 2}$ und $\vec{H}_{\tan 1} = \vec{H}_{\tan 2}$

$$\underline{E}_{y1}(x=h) = \underline{E}_{y2}(x=h) \Rightarrow \underline{B}_1 \sin(\underline{k}_{x1} h) = \underline{B}_2 \sin(\underline{k}_{x2} h)$$

$$\underline{E}_{z1}(x=h) = \underline{E}_{z2}(x=h) \equiv 0 \quad \checkmark \quad \underline{H}_{y1}(x=h) = \underline{H}_{y2}(x=0) \equiv 0 \quad \checkmark$$

$$\underline{H}_{z1}(x=h) = \underline{H}_{z2}(x=h) \Rightarrow -\underline{k}_{x1} \underline{B}_1 \cos(\underline{k}_{x1} h) = \underline{k}_{x2} \underline{B}_2 \cos(\underline{k}_{x2} h)$$

Charakteristische Gl. \swarrow oder mit $\tan(\cdot)$ und Kehrwert

$$\underline{k}_{x1} \cot(\underline{k}_{x1} h) = -\underline{k}_{x2} \cot(\underline{k}_{x2} h) \quad \text{mit } \underline{k}_{x_i}^2 = k_i^2 - \beta^2$$

d) Fall $\epsilon_1 = \epsilon_2 \quad k_1 = k_2 \quad k_{x1} = k_{x2} \neq 0$

Charach. Gl:

$$\underline{k}_{x1} \cot(\underline{k}_{x1} h) = -\underline{k}_{x2} \cot(\underline{k}_{x2} h)$$

$$\text{da } \underline{k}_{x1} = \underline{k}_{x2} : \quad = -\underline{k}_{x1} \cot(\underline{k}_{x1} h)$$

$$\Rightarrow \underline{k}_{x1} \cot(\underline{k}_{x1} h) = 0 \Rightarrow \cot(\underline{k}_{x1} h) = 0 \quad \text{da } \underline{k}_{x1} \neq 0$$

$$\Rightarrow \underline{k}_{x1} = \pm \frac{\pi}{2h} ; \pm \frac{3\pi}{2h} ; \pm \frac{5\pi}{2h} ; \dots$$

andere char. Gl: $\underline{k}_{x2} \tan(\underline{k}_{x1} h) = -\underline{k}_{x1} \tan(\underline{k}_{x2} h)$

$$\Rightarrow \tan(\underline{k}_{x1} h) = 0 \quad (\text{analog wie oben}) \Rightarrow \underline{k}_{x1} = 0 ; \pm \frac{\pi}{h} ; \pm \frac{2\pi}{h} ; \pm \frac{3\pi}{h}$$

Für TE_x Grundwelle (TE_{x10}) $\underline{k}_{x1} = \underline{k}_{x2} = \frac{\pi}{2h}$

Grenzfrequ: ω_c mit $\beta(\omega_c) = 0$: $\underline{k}_{x1}^2 = k_1^2 - \beta^2 = k_1^2 = \omega_c^2 \epsilon_1 \mu_0 \Rightarrow \omega_c = \frac{\pi}{2h} \cdot \frac{1}{\sqrt{\epsilon_1 \mu_0}}$

10 a) TE_x Hybridwelle: ($E_x \equiv 0$)

$$\vec{E}_i = f_i(x, z) \vec{e}_x = \tilde{f}_i(x) e^{-j\beta z} \vec{e}_x \quad i=1,2$$

$$\vec{G}_i = 0 \Rightarrow E_x = 0$$

$$\text{mit } \beta^2 = \omega^2 \epsilon_{eff}(\omega) \mu_0, \quad k_i^2 = \omega^2 \epsilon_i \mu_0$$

Helmholtz gl.: mit $k_{xi}^2 = k_i^2 - \beta^2$

$$\left(\frac{d^2}{dx^2} - \beta^2 + k_i^2 \right) \tilde{f}_i(x) = 0 \quad (=) \quad \left(\frac{d^2}{dx^2} + k_{xi}^2 \right) \tilde{f}_i(x) = 0$$

$$\tilde{f}_1(x) = B_1 \sin(k_{x1} x)$$

$$\tilde{f}_2(x) = B_2 \sin(k_{x2} (2h-x))$$

b) Gebiet 1: Randbed.: $\vec{E}_{tan1} = 0$ und $\vec{H}_{n1} = 0$

$$E_{x1}(y=0)=0 \quad \checkmark \quad E_{x1}(y=b)=0 \quad \checkmark$$

$$E_{z1}(y=0)=0 \quad \checkmark \quad E_{z1}(y=b)=0 \quad \checkmark$$

$$E_{y1}(y=0)=0 \quad \checkmark \quad E_{y1}(y=b)=0 \quad \checkmark$$

$$\vec{E}_{y1}(x=0)=0 \Rightarrow \underline{A_1=0}$$

$$E_{z1}(x=0)=0 \quad \checkmark$$

$$E_{x1}(x=0)=0 \Rightarrow A_1=0 \quad \checkmark$$

Gebiet 2: Randbed.: $\vec{E}_{tan2} = 0$ und $\vec{H}_{n2} = 0$

$$\Rightarrow E_{x2}(y=0)=0 \quad \checkmark \quad E_{x2}(y=b)=0 \quad \checkmark$$

$$E_{z2}(y=0)=0 \quad \checkmark \quad E_{z2}(y=b)=0 \quad \checkmark$$

$$E_{y2}(y=0)=0 \quad \checkmark \quad E_{y2}(y=b)=0 \quad \checkmark$$

$$E_{y2}(x=2h)=0 \Rightarrow \underline{A_2=0}$$

$$E_{z2}(x=2h)=0 \quad \checkmark$$

$$E_{x2}(x=2h)=0 \Rightarrow A_2=0 \quad \checkmark$$

Gebiet 1: $E_{x1} \equiv 0$ da $g_1 = 0$

$$E_{y1} = -\frac{\partial A_1}{\partial z} = j\beta \tilde{f}_1$$

$$E_{y1} = j\beta B_1 \sin(k_{x1} x) e^{-j\beta z}$$

$$E_{z1} = \frac{\partial A_1}{\partial y} \equiv 0 \quad \text{da } f_1(x, z)$$

$$\underline{H}_{x1} = \frac{\beta^2}{j\omega\mu_0} (\underline{B}_1 \sin(\underline{k}_{x1} \cdot x)) e^{-j\beta z} \quad (\underline{k}_1^2 + \frac{\partial^2}{\partial x^2}) \underline{f}_1 = \beta^2 \underline{f}_1$$

$$\underline{H}_{x1} = \frac{1}{j\omega\mu_0} \frac{\partial^2 \underline{f}_1}{\partial x \partial y} \equiv 0 \quad \text{da } \underline{f}_1(x, z)$$

$$\underline{H}_{z1} = \frac{1}{j\omega\mu_0} \frac{\partial^2 \underline{f}_1}{\partial x \partial y} = -\frac{\beta}{\omega\mu_0} \frac{\partial \underline{f}_1}{\partial x} = -\frac{\beta \underline{k}_{x1}}{\omega\mu_0} (\underline{B}_1 \cos(\underline{k}_{x1} x)) e^{-j\beta z}$$

Gebiet 2 $\underline{E}_{x2} \equiv 0 \quad \underline{E}_{z2} \equiv 0 \quad \underline{H}_{y2} \equiv 0$

$$\underline{E}_{y2} = j\beta \underline{B}_2 \sin(\underline{k}_{x2} (2h-x)) e^{-j\beta z}$$

$$\underline{H}_{x2} = \frac{\beta^2}{j\omega\mu_0} \underline{B}_2 \sin(\underline{k}_{x2} (2h-x)) e^{-j\beta z}$$

$$\underline{H}_{z2} = -\frac{\beta \underline{k}_{x2}}{\omega\mu_0} (-\underline{B}_2 \cos(\underline{k}_{x2} (2h-x))) e^{-j\beta z}$$

c) Stetigkeit bei $x=h$: $\vec{E}_{\tan 1} = \vec{E}_{\tan 2}$ und $\vec{H}_{\tan 1} = \vec{H}_{\tan 2}$

$$\underline{E}_{y1}(x=h) = \underline{E}_{y2}(x=h) \Rightarrow \underline{B}_1 \sin(\underline{k}_{x1} h) = \underline{B}_2 \sin(\underline{k}_{x2} h)$$

$$\underline{E}_{z1}(x=h) = \underline{E}_{z2}(x=h) \equiv 0 \quad \checkmark \quad \underline{H}_{y1}(x=h) = \underline{H}_{y2}(x=0) \equiv 0 \quad \checkmark$$

$$\underline{H}_{z1}(x=h) = \underline{H}_{z2}(x=h) \Rightarrow -\underline{k}_{x1} \underline{B}_1 \cos(\underline{k}_{x1} h) = \underline{k}_{x2} \underline{B}_2 \cos(\underline{k}_{x2} h)$$

Charakteristische Gl. \swarrow oder mit $\tan(\cdot)$ und Kehrwert
 $\underline{k}_{x1} \cot(\underline{k}_{x1} h) = -\underline{k}_{x2} \cot(\underline{k}_{x2} h) \quad \text{mit } \underline{k}_{x_i}^2 = k_i^2 - \beta^2$

d) Fall $\epsilon_1 = \epsilon_2 \quad k_1 = k_2 \quad k_{x1} = k_{x2} \neq 0$

Charach. Gl:

$$\underline{k}_{x1} \cot(\underline{k}_{x1} h) = -\underline{k}_{x2} \cot(\underline{k}_{x2} h)$$

$$\text{da } \underline{k}_{x1} = \underline{k}_{x2} : \quad = -\underline{k}_{x1} \cot(\underline{k}_{x1} h)$$

$$\Rightarrow \underline{k}_{x1} \cot(\underline{k}_{x1} h) = 0 \Rightarrow \cot(\underline{k}_{x1} h) = 0 \quad \text{da } \underline{k}_{x1} \neq 0$$

$$\Rightarrow \underline{k}_{x1} = \pm \frac{\pi}{2h} ; \pm \frac{3\pi}{2h} ; \pm \frac{5\pi}{2h} ; \dots$$

andere char. Gl: $\underline{k}_{x2} \tan(\underline{k}_{x1} h) = -\underline{k}_{x1} \tan(\underline{k}_{x2} h)$

$$\Rightarrow \tan(\underline{k}_{x1} h) = 0 \quad (\text{analog wie oben}) \Rightarrow \underline{k}_{x1} = 0 ; \pm \frac{\pi}{h} ; \pm \frac{2\pi}{h} ; \pm \frac{3\pi}{h}$$

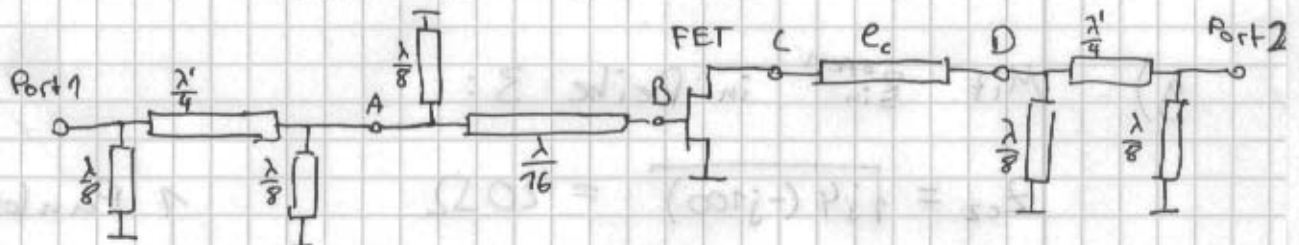
Für TE_x Grundwelle (TE_{x10}) $\underline{k}_{x1} = \underline{k}_{x2} = \frac{\pi}{2h}$

Grenzfrequ: ω_c mit $\beta(\omega_c) = 0$: $\underline{k}_{x1}^2 = k_1^2 - \beta^2 = k_1^2 = \omega_c^2 \epsilon_1 \mu_0 \Rightarrow \omega_c = \frac{\pi}{2h} \cdot \frac{1}{\sqrt{\epsilon_1 \mu_0}}$

Aufgabe 4

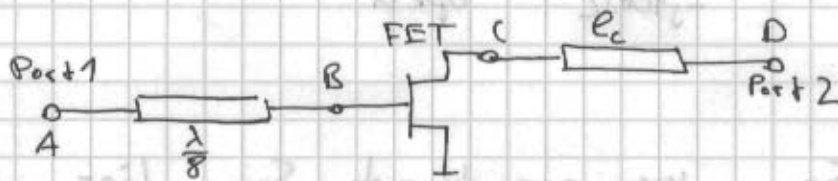
a) Port 1: $\underline{U}_1 = \frac{U_g}{2} + \frac{U_g}{2}$

Port 4: $\underline{U}_4 = \frac{U_g}{2} - \frac{U_g}{2}$



Odd-mode bei f_0

b) $\frac{\lambda}{8} \rightarrow \frac{\lambda}{4}$ $K \xrightarrow{\frac{\lambda}{4}} LL$ $\frac{\lambda'}{4} \rightarrow \frac{\lambda'}{2}$



Odd-mode bei $2f_0$

c) $\underline{Z}_1 = \frac{\underline{U}_1}{\underline{I}_1} = \frac{U_2 \cos(\beta l) + j Z_0 \sin(\beta l) (-I_2)}{U_2 j Y_0 \sin(\beta l) + \cos(\beta l) (-I_2)}$

$\underline{Z}_{in}^{open} = \underline{Z}_1 (I_2 = 0) = -j Z_0 \cot(\beta l)$ 2 Punkte

$\underline{Z}_{in}^{short} = \underline{Z}_1 (U_2 = 0) = j Z_0 \tan(\beta l)$ 2 Punkte

d) $Z_0 = \sqrt{\underline{Z}_{in}^{open} \underline{Z}_{in}^{short}}$ 2 Punkte

$Z_{c1} = \sqrt{(-j100)(j25)} = 50 \Omega$ 1 Punkt

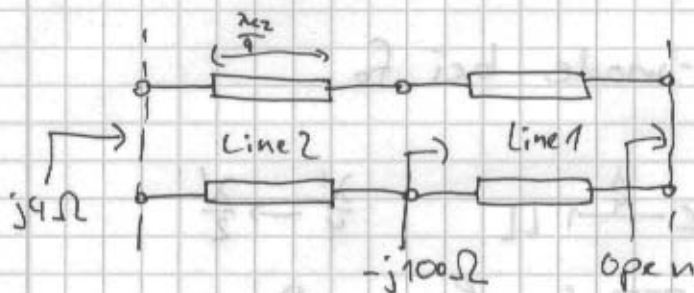
e) $\theta = \arctan \sqrt{-\frac{Z_{in}^{short}}{Z_{in}^{open}}}$ 2 Punkte

$\theta_{c1} = \arctan \sqrt{-\frac{j25}{-j100}} = \arctan\left(\frac{1}{2}\right) = 26,6^\circ$ 1 Punkt

f) $\ell_{c2} = \frac{\lambda_{c2}}{4}$ oder $\theta_{c2} = 90^\circ$ 1 Punkt

g) Mit Z_{in}^{open} in Reihe 3:

$Z_{c2} = \sqrt{j4(-j100)} = 20 \Omega$ 1 Punkt



h) • From S_{FET} we see that S_{22} lies on the real axis of reflection coefficient plane. In addition FET is unilateral, therefore output impedance of transistor is real.

• To transform $Z_0 = 50 \Omega$ into the real impedance Z_{out}^{FET} we need a $\frac{\lambda}{4}$ -transformator, so that only Line 2 can be used.

• Impedance seen by FET:

$Z_{seen}^{FET} = \frac{(20 \Omega)^2}{50 \Omega} = 8 \Omega$

Aufgabe 5:

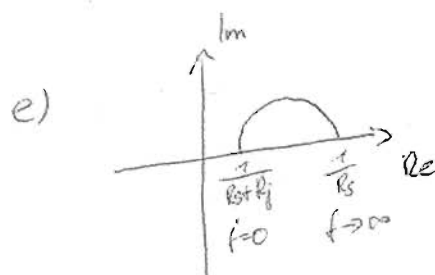
- a) Das Bauteil ist eine (Schottky-)Diode. Die Eigenschaft: Nichtlinear
 b) ESB 0. Ordnung

AP1: $\frac{1}{R_j}$

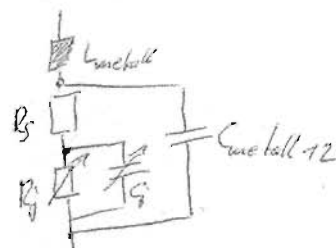
AP2: $\frac{1}{C_j}$

c) $R_j = \frac{1}{0,085} = 12,5 \Omega$ und $|X_j| = \frac{1}{0,0055} \Rightarrow C_j = \frac{Y_j}{\omega} = \frac{5 \cdot 10^{-3}}{10 \cdot 10^6} = 0,5 pF$

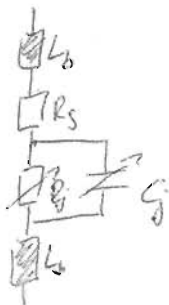
d) Intrinsic Bauteil



f) Kapazität zwischen Metall 1 und Metall 2
 (parallel zu intrinsic)
 Induktivität der Metall 1 Leitung



g) Bandstrahl \Rightarrow Spule

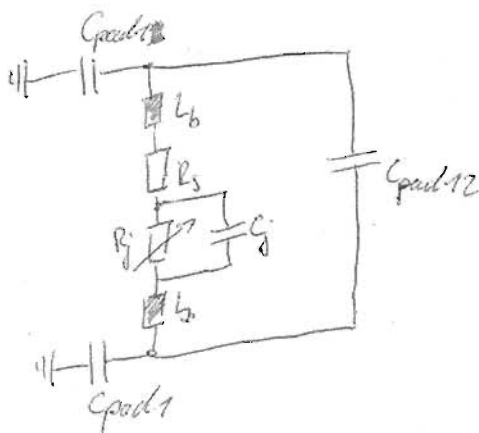


$$\omega = \frac{1}{\sqrt{LC}} \Rightarrow L = \frac{1}{\omega^2 C}$$

$$L = 1,25 nH = 2 \cdot L_b$$

$$R_s = \frac{1}{0,125} \Omega = 8 \Omega$$

h) Padkapazitäten



Aufgabe 6:

a) ~~Lösung 4. Unterpunkt.~~

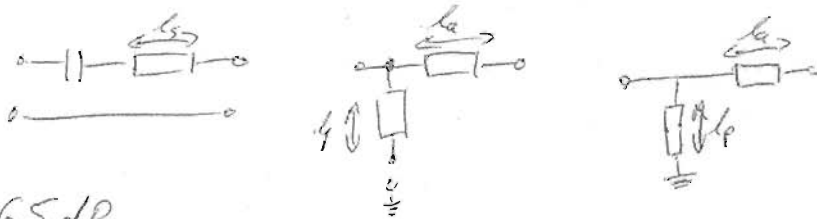
Zwei Antworten akzeptiert:

- 1. Transistor dessen S_{22}^* den geringsten Abstand zu Γ_L hat ermöglicht das breitbandigste Anpassungsnetzwerk mit geringster Güte
- 1. Transistor dessen S_{22} auf Kreisen konst. Güte am nächsten zu $\Gamma_L = 0$ liegt, hat geringste Güte

b) Mit dem vorgegebenen Adj. netz. ist nur ~~eine~~ mit Transistor 3 Leistungsanpassung ~~möglich~~ möglich

c) $\Gamma_p = -j0,373, l_2 = 0,041\lambda$

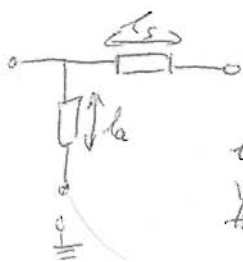
d) Kondensator in Serie oder Strickleitung



e) $F_1 = 3,65 \text{ dB}$
 $G_{q1} = 0 \text{ dB}$

f) aus Smith-Chart: $\text{Re}\{\Gamma_{r,\min}\} = -0,364, \text{Im}\{\Gamma_{r,\min}\} = 0,108$
$$\Gamma_{r,\min} = \frac{1 - \Gamma_{r,\min}}{1 + \Gamma_{r,\min}} = \frac{1 - \text{Re}\{\Gamma_{r,\min}\} - j\text{Im}\{\Gamma_{r,\min}\}}{1 + \text{Re}\{\dots\} + j\text{Im}\{\dots\}}$$

g)



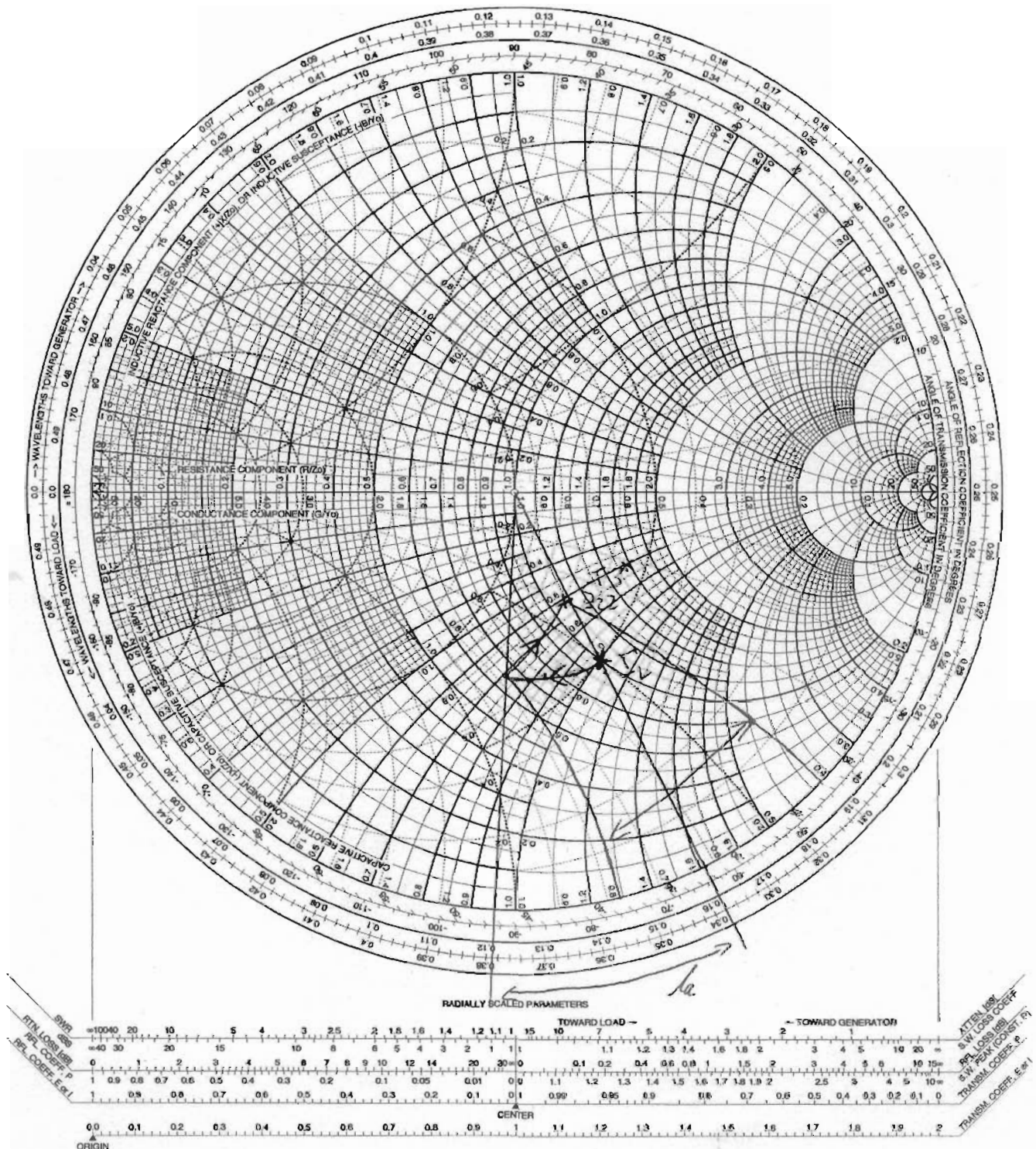
$$l_s = 0,140\lambda$$

$$\Gamma_p = j1,11, l_p = 1,33\lambda$$

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Hilfsblatt 3 zu Aufgabe 6, Unterpunkt g)

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