

A1

Lösung (H07)

a) Gesamtladung des Zylinders $\stackrel{!}{=} 0$

$$\int_+ \cdot 2 \cdot l \cdot \sigma \cdot r_i^2 = - \int_- \cdot 2 \cdot l \cdot \hat{a} \cdot (r_a^2 - (r_a - d)^2)$$

$$\Rightarrow \hat{a} \cdot r_i^2 = \hat{a} \cdot r_a^2 - \hat{a} \cdot (r_a^2 - 2r_a d + d^2)$$

$$\Rightarrow r_i^2 = 2r_a d - d^2$$

$$\Rightarrow d^2 - 2r_a d + r_a^2 = -r_i^2 + r_a^2$$

$$\Rightarrow \cancel{(d - r_a)^2} = r_a^2 - r_i^2 \quad d = r_a \pm \sqrt{r_a^2 - r_i^2}$$

Rückw. von $d < r_a$

$$d = r_a - \sqrt{r_a^2 - r_i^2}$$

b) $\text{rot } \vec{H} = \vec{J} + \vec{J}_d$

$$\boxed{\text{div rot } \vec{A} = 0}$$

$$\text{div rot } \vec{H} = 0 = \text{div } \vec{J} + \text{div } \vec{J}_d$$

$$\text{div } \vec{J} + \frac{\partial \rho}{\partial t} = 0 \quad \text{da } \text{div } \vec{J}_d = \rho$$

c) Gauß'sches Gesetz $\vec{J} = \sigma_{zy} \vec{E}$

$$\text{div } \vec{J} = \text{div}(\sigma_{zy} \cdot \vec{E}) = \sigma_{zy} \cdot \text{div } \vec{E}$$

$$\sigma_{zy} \cdot \frac{\rho}{\epsilon_0 \epsilon_r} + \dot{\rho} = 0$$

$$\Rightarrow \frac{\dot{\rho}}{\rho} = - \frac{\sigma_{zy}}{\epsilon_0 \epsilon_r}$$

Lösung für $0 \leq r \leq r_i$: $-\frac{\sigma_{zy}}{\epsilon_0 \epsilon_r} \cdot t$

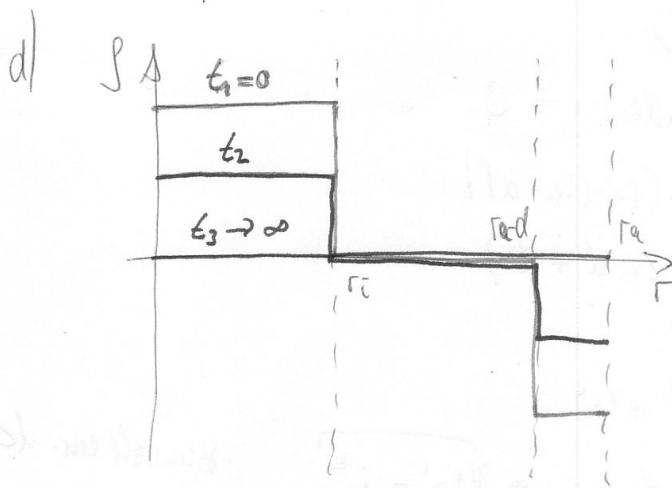
$$\rho(t) = \rho_0 \cdot e$$

$$\underline{r_i \leq r \leq r_a - d}$$

$$\rho(t) = 0$$

$$\underline{r_a - d \leq r \leq r_a}: -\frac{\sigma_{zy}}{\epsilon_0 \epsilon_r} \cdot t$$

$$\rho(t) = \rho_0 \cdot e$$



e)
$$I' = -\dot{q}(t) \cdot \hat{u} \cdot r_i^2$$

$$= + \frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} \cdot \dot{q}(t) \cdot e^{-\frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} t} \cdot \hat{u} \cdot r_i^2$$

$$I'(t) = \frac{I(t)}{\Delta l} = \frac{\dot{q}(t) \cdot \Delta V}{\Delta l} = \frac{\dot{q}(t) \cdot \Delta l}{\Delta l}$$

\dot{q} = Lösung für $0 \leq r \leq r_i$

f)

$$D_r(r, t) = \frac{2 \cdot l \cdot \dot{q}(t) \cdot \hat{u} \cdot r_i^2}{2 \cdot l \cdot 2 \cdot \hat{u} \cdot r_i} = \dot{q}(t) \cdot e^{-\frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} t} \cdot \frac{r_i}{2}$$

abgeschl. Ladung
Oberfläche

allgemein:
$$D_r(r, t) = \frac{\dot{q}(t) \cdot e^{-\frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} t} \cdot r_i^2}{2 \cdot r}$$

für $r_i < r < r_a - d$

$$\phi = \vec{J} \cdot \vec{E} = \vec{J} \cdot \frac{\vec{D}}{\epsilon_0 \epsilon_r} = J_r \frac{D_r}{\epsilon_0 \epsilon_r}$$

$$|\vec{J}| = J_r = \frac{I'}{2 \pi r} = \dot{q}(t) \cdot \frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} \cdot e^{-\frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} t} \cdot \frac{\hat{u} \cdot r_i^2}{2 \pi r}$$

$$\rho = \frac{1}{\epsilon_0 \epsilon_r} \dot{q}(t) \cdot \frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} \cdot e^{-\frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} t} \cdot \frac{\hat{u} \cdot r_i^2}{2 \pi r} \cdot \frac{\dot{q}(t) \cdot e^{-\frac{\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} t} \cdot r_i^2}{2 r} =$$

$$= \frac{1}{(\epsilon_0 \epsilon_r)^2} \sqrt{\epsilon_2} \cdot \dot{q}(t)^2 \cdot e^{-\frac{2\sqrt{\epsilon_2}}{\epsilon_0 \epsilon_r} t} \cdot \frac{\hat{u} \cdot r_i^4}{4 \pi r^2}$$

Lösung #07

a) $\vec{u} = \frac{\vec{S}}{|\vec{S}|} = \frac{1}{\sqrt{1^2 + 2^2}} (-\vec{e}_1 + 2\vec{e}_2) = \frac{1}{\sqrt{5}} (-\vec{e}_1 + 2\vec{e}_2)$

$z = \frac{|\vec{E}|}{|\vec{H}|}$ in $(0,0,0)$ oder $\vec{H} = \frac{1}{z} (\vec{u} \times \vec{E})$ bzw. $\vec{E} = -z (\vec{u} \times \vec{H})$

$\vec{E}(0,0,0)$ über $\vec{S}(0,0,0) = \vec{E}(0,0,0) \times \vec{H}^*(0,0,0)$ $\vec{E} \times \vec{H}^* = -z (\vec{u} \times \vec{H}) \times \vec{H}^*$

$\vec{E} \times \vec{H}^* = \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ E_x & E_y & E_z \\ j \frac{\delta E_0}{z_0} & 0 & 0 \end{vmatrix} = \vec{S}(0,0,0)$

$\vec{S} = z \cdot \vec{H}^* \times (\vec{u} \times \vec{H})$

$\vec{S} = z \cdot [\vec{u} \cdot (\vec{H} \cdot \vec{H}^*) - \underbrace{(\vec{u} \cdot \vec{H}^*) \cdot \vec{H}}_{=0}]$
 $= z \cdot \vec{u} (\vec{H} \cdot \vec{H}^*)$

Komponentenvergleich:

$E_z = -j \frac{\delta E_0}{z_0}$; $E_y = -j E_0$

Weiterhin gilt: $\vec{E} \cdot \vec{H} = 0$

$\Rightarrow E_x = 0$

$z = \frac{|\vec{E}|}{|\vec{H}|} = \frac{\sqrt{5} E_0 z_0}{2 \cdot \delta E_0} = \frac{\sqrt{5}}{16} z_0$

nicht so einfach!

$\frac{4 E_0^2}{z_0} \vec{u} \cdot \vec{H} = z \cdot \frac{64 E_0^2}{z_0^2} \vec{u} \cdot \vec{H}$

$\Rightarrow z = \frac{\sqrt{5}}{16} z_0$

$z \cdot \frac{\sqrt{\mu}}{\epsilon} = \sqrt{\frac{\mu_0 \mu_r}{\epsilon_0 \epsilon_r}} = \sqrt{\frac{\mu_0}{\epsilon_0 \epsilon_r}} = \frac{1}{\sqrt{\epsilon_r}} z_0$

$\frac{1}{\sqrt{\epsilon_r}} = \frac{\sqrt{5}}{16} \Rightarrow \epsilon_r = \frac{16^2}{5} = 51,2$

$k = \frac{2\pi \cdot \vec{u} \cdot \vec{u}}{\lambda} = \frac{\omega}{c} \cdot \vec{u} = \omega \sqrt{\epsilon_r \epsilon_0 \mu_0} \cdot \vec{u} = k_0 \sqrt{\epsilon_r} \cdot \vec{u} = \frac{16}{\sqrt{5}} k_0 \cdot \vec{u}$

b) $\vec{E}(x,y,z) = \vec{E}(0,0,0) \cdot e^{-j k r}$

$\vec{u} \cdot \vec{r} = k_0 \frac{16}{\sqrt{5}} \frac{1}{\sqrt{5}} \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = k_0 \frac{16}{5} (-y + 2z)$

$\Rightarrow \vec{E} = -j \frac{E_0}{2} (2\vec{e}_2 + \vec{e}_3) \cdot e^{-j k_0 \frac{16}{5} (-y + 2z)}$

analog: $\vec{H} = j \frac{\delta E_0}{z_0} \vec{e}_1 \cdot e^{-j k_0 \frac{16}{5} (-y + 2z)}$

$$c) \vec{E}(x, y, z, t) = \vec{E}(x, y, z) \cdot e^{-j\omega t} = -j \frac{E_0}{2} (2 \cdot \vec{e}_y + \vec{e}_z) \cdot e^{-j[k_0 \frac{16}{5} (-y+2z) - \omega t + \frac{\pi}{2}]} \\ = \frac{E_0}{2} (2 \vec{e}_y + \vec{e}_z) \cdot e^{-j[k_0 \frac{16}{5} (-y+2z) - \omega t + \frac{\pi}{2}]}$$

$$\vec{E}(x, y, z, t) = \operatorname{Re} \{ \vec{E}(x, y, z, t) \}$$

$$\vec{E}(x, y, z, t) = \frac{E_0}{2} (2 \vec{e}_y + \vec{e}_z) \cdot \left[\cos(k_0 \frac{16}{5} (-y+2z) - \omega t + \frac{\pi}{2}) - j \sin(k_0 \frac{16}{5} (-y+2z) - \omega t + \frac{\pi}{2}) \right]$$

$$\vec{E}(x, y, z, t) = \frac{E_0}{2} (2 \vec{e}_y + \vec{e}_z) \cdot \left\{ -\sin[k_0 \frac{16}{5} (-y+2z) - \omega t] \right\} \quad \text{da: } \cos(t + \frac{\pi}{2}) = \sin(t)$$

linear polarisierte Welle

d) allg.: $\vec{E}_{\text{tan}} = 0$ an ideal leitender Wand

$$\text{hier: } (\vec{E}_{\text{hin}} + \vec{E}_{\text{rück}}) \Big|_{\substack{x=0 \\ y=0 \\ z=0}} = 0$$

h: hinlaufend

r: rücklaufend

e) stehende Welle

Die Welle wird vollständig reflektiert, keine Leistung wird im Zeitmittel

$$\text{Transportleistung} = \overline{S} = 0$$

Lösung (H07)

Wellengleichung: $\Delta \underline{g}(x, y, z) + k^2 \underline{g}(x, y, z) = 0$ *

Separationsansatz: $\underline{g}(x, y, z) = \underline{u}(x) \cdot \underline{v}(y) \cdot e^{-j\beta z}$

allg. Lsg: $\underline{u}(x) = A \cdot \cos(k_x x) + B \cdot \sin(k_x x)$
 $\underline{v}(y) = C \cdot \cos(k_y y) + D \cdot \sin(k_y y)$

* $\Rightarrow 0 = -k_x^2 - k_y^2 - \beta^2 + k^2 \Rightarrow \beta(\omega) = \sqrt{\omega^2 \epsilon \mu - k_x^2 - k_y^2}$

c) \underline{G}_1 & \underline{G}_3 : ideal elektrisch leitende Wände

$\vec{E}_{tan} = \vec{0}$ d.h. $0 = E_x(x, 0, z) = E_x(x, b, z)$
 $0 = E_z(x, 0, z) = E_z(x, b, z)$

\underline{G}_2 & \underline{G}_4 : ideal magnetische Wände:

$\vec{H}_{tan} = \vec{0}$ d.h. $0 = H_y(0, y, z) = H_y(a, y, z)$
 $(H_z = 0, \text{ da TM-Welle})$

$H_y = (\vec{\nabla} \times \underline{g}(x, y, z) \cdot \vec{e}_z)_y = -\frac{\partial}{\partial x} g(x, y, z)$

$x=0$: $0 = H_y(0, y, z) = -\underline{u}'(0) \underline{v}(y) e^{-j\beta z}$
 $\Rightarrow 0 = A + B k_x \Rightarrow B = 0$

$x=a$: $0 = H_y(a, y, z) = -\underline{u}'(a) \underline{v}(y) e^{-j\beta z}$
 $\Rightarrow k_x = \frac{c_1 \cdot a}{a} \quad c_1 = 1, 2, 3$

\underline{G}_1 & \underline{G}_3 :

$y=0$: $0 = \frac{\partial}{\partial x} g(x, y, z) \Big|_{y=0} = \underline{u}'(x) \cdot \underline{v}(0) \cdot e^{-j\beta z}$

$\underline{v}(0) = 0 \Rightarrow C = 0$

$y=b$: $\underline{v}(b) = 0 \Rightarrow D \cdot \sin(k_y b) = 0$

$\Rightarrow k_y = \frac{c_2 \cdot b}{b} \quad c_2 = 1, 2, 3$

Somit ist $g(x, y, z) = A \cdot \cos\left(\frac{c_1 \cdot x}{a}\right) \sin\left(\frac{c_2 \cdot y}{b}\right) e^{-j\beta z}$ $A = \text{const}$ c_1, c_2

$$d) \underline{H} = \vec{\nabla} \times \underline{g}(x, y, z) = \begin{pmatrix} \frac{\partial}{\partial y} g(x, y, z) \\ -\frac{\partial}{\partial x} g(x, y, z) \\ 0 \end{pmatrix}$$

$$b = a: \quad k_x = \frac{c_1 \cdot a}{a} \quad k_y = \frac{c_2 \cdot a}{a}$$

$$\Rightarrow H_x = \frac{\partial}{\partial y} g(x, y, z) = \frac{c_2 \cdot a}{a} \cdot A \cdot \cos\left(\frac{c_1 \cdot x}{a}\right) \cdot \cos\left(\frac{c_2 \cdot y}{a}\right) \cdot e^{-j\beta z}$$

$$H_y = -\frac{\partial}{\partial x} g(x, y, z) = -\frac{c_1 \cdot a}{a} \cdot A \cdot \sin\left(\frac{c_1 \cdot x}{a}\right) \cdot \sin\left(\frac{c_2 \cdot y}{a}\right) \cdot e^{-j\beta z}$$

$$\text{mit } c_1 = u, \quad c_2 = u \quad \text{und} \quad A_{\text{max}} = \frac{a \cdot a}{a} \cdot A$$

$$\text{folgt: } H_x = A_{\text{max}} \cos\left(\frac{u \cdot x}{a}\right) \cos\left(\frac{u \cdot y}{a}\right) e^{-j\beta z}$$

$$H_y = -\frac{u}{u} A_{\text{max}} \sin\left(\frac{u \cdot x}{a}\right) \sin\left(\frac{u \cdot y}{a}\right) e^{-j\beta z}$$

$$e) \underline{A}_5: \quad \underline{H}_{\text{tot}} = 0 \quad H_z \equiv 0 \quad (\text{TM-Welle})$$

$$\underline{H}_y = \left(\frac{3}{7} \cdot a, y, z\right) = 0$$

$$f) \underline{A}_6: \quad \underline{E}_{\text{tot}} = 0 \quad E_z(x, \frac{1}{2}a, z) = 0$$

$$E_x(x, \frac{1}{2}a, z) = 0$$

$$f) \underline{A}_5: \quad H_y\left(\frac{3}{7}a, y, z\right) = 0$$

$$\Rightarrow 0 = \sin\left(k_x \cdot \frac{3}{7}a\right) = \sin\left(\frac{u \cdot a}{a} \cdot \frac{3}{7}a\right) = \sin\left(3 \cdot \frac{u \cdot a}{7}\right) \quad \text{ist erfüllt für } \frac{u}{7} = 1, 2, 3, \dots$$

$$\underline{A}_6: \quad E_z(x, \frac{1}{2}a, z) = 0$$

$$\Rightarrow 0 = \sin\left(k_y \cdot \frac{1}{2}a\right) = \sin\left(\frac{u}{2} \cdot a\right) \quad \text{ist erfüllt für } u = 2, 4, 6$$

$$\omega^2 \cdot \epsilon \cdot \mu = \beta^2 + k_x^2 + k_y^2$$

$$\omega_{\text{min}} = \sqrt{\frac{\beta^2 + \left(\frac{u}{a} \cdot a\right)^2 + \left(\frac{u}{a} \cdot a\right)^2}{\epsilon \cdot \mu}}$$

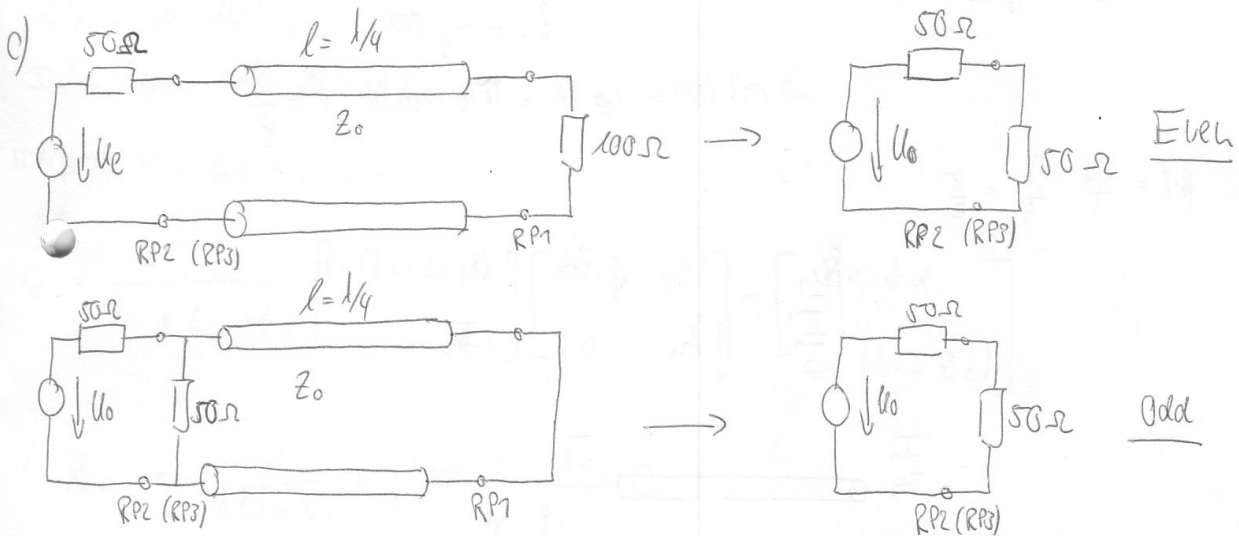
$$\omega_{\text{min}} = \sqrt{\frac{0 + \left(\frac{1}{a} \cdot a\right)^2 + \left(\frac{2}{a} \cdot a\right)^2}{\epsilon \cdot \mu}} = \frac{\sqrt{5}}{\sqrt{\epsilon \mu}} \cdot a$$

$$f_{\text{min}} = \frac{\omega_{\text{min}}}{2\pi a} = \frac{\sqrt{5}}{2\pi \sqrt{\epsilon \mu}}$$

Lsg. #07

a)
$$\underline{S} = \begin{bmatrix} S_{11} & S_{12} & S_{13} \\ S_{21} & S_{22} & S_{23} \\ S_{31} & S_{32} & S_{33} \end{bmatrix}$$

- b) Reziprozität: $S_{12} = S_{21}, S_{13} = S_{31}, S_{23} = S_{32}$
 Symmetrie: $S_{22} = S_{33}, S_{21} = S_{31}$
 unabhängige S-Parameter: $S_{11}, S_{12}, S_{23}, S_{22}$



- d) Spannung an Tor 3: $U_{g3} = 2V = 1V + 1V = U_{g3}^e + U_{g3}^o$ (1)
 Spannung an Tor 2: $U_{g2} = 0V = 1V - 1V = U_{g2}^e + U_{g2}^o$ (2)
 $U_2 = U_2^e + U_2^o$
 even mode circuit $\Rightarrow U_2^e = 0.5V$
 odd mode circuit $\Rightarrow U_2^o = -0.5V$ } $\Rightarrow U_2 = 0V$

- e) Z_L : Impedanz am Eingang der offenen 50Ω Leitung der Länge l_0
 Die Schaltung ist symmetrisch, Einspeisung an Tor 1 ruft die gleichen Spannungen an Tor 2 und 3 hervor. Deswegen kann der 100Ω Widerstand weggelassen werden.

$$Z_{in} = \frac{1}{2} \frac{Z_0^2}{Z_r} \quad \text{und} \quad S_{11} = \frac{Z_{in} - 50}{Z_{in} + 50} \quad S_{11} = 1 \angle 90^\circ = j$$

Der Smith Chart kann benutzt werden, um den Wert der Eingangs impedanz zu bestimmen, wenn der Reflexionskoeffizient von $S_{11} = 1 \angle 90^\circ = j$ bzw. $Z_{in} = j 50\Omega$ zu erreichen.

Ohne Smith Chart:

$$Z_{in} = 50 \cdot \frac{1 + \Gamma_{in}}{1 - \Gamma_{in}} = 50 \cdot \frac{1 + j}{1 - j} = 50 \frac{\sqrt{2} \angle 45^\circ}{\sqrt{2} \angle -45^\circ} = 50 \angle 90^\circ = j50 \Omega$$

$$\text{von (1)} \quad Z_x = \frac{1}{2} \frac{Z_0^2}{Z_{in}} = \frac{1}{2} \frac{(\sqrt{2} \cdot 50)^2}{j50} = -j50 \Omega \Rightarrow Z_x^{\text{norm}} = -j$$

Bestimmung von l ohne Smith Chart:

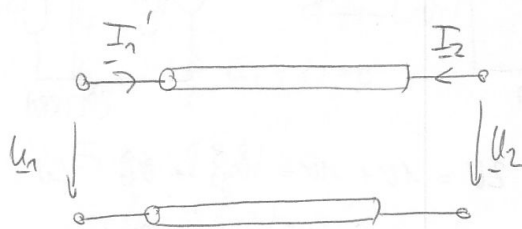
$$Z_x = Z_0 \frac{Z_L + j Z_0 \tan(\beta l)}{Z_0 + j Z_L \tan(\beta l)} \quad \text{mit } Z_L = \infty \quad Z_x = -j Z_0 \cot(\beta l) = -j50 \cot(\beta l)$$

$$Z_x = -j50$$

$$\Rightarrow \cot(\beta l) = 1 \Leftrightarrow \beta l = \pi/4 \quad \text{und} \quad l = \frac{1}{\beta}$$

$$f) \quad \beta \cdot l = \frac{2\pi}{\lambda} \cdot \frac{1}{4} = \frac{\pi}{2}$$

$$\begin{bmatrix} \underline{U}_1 \\ \underline{I}_1' \end{bmatrix} = \begin{bmatrix} 0 & j Z_{01} \\ j Y_{01} & 0 \end{bmatrix} \begin{bmatrix} \underline{U}_2 \\ -\underline{I}_2 \end{bmatrix}$$



$$\underline{U}_1 = j Z_{01} (-\underline{I}_2)$$

$$\underline{U}_2 = Z_{ref2} (-\underline{I}_2)$$

$$\frac{\underline{U}_1}{\underline{U}_2} = j \left(\frac{Z_{01}}{Z_{ref2}} \right)$$

$$\underline{U}_2 = -j \left(\frac{Z_{ref2}}{Z_{01}} \right) \cdot \underline{U}_1 = -j \left(\frac{50/\sqrt{2}}{75/\sqrt{2}} \right) \cdot \underline{U}_1 = -j \left(\frac{50}{75} \right) \underline{U}_1$$

$$\underline{U}_3 = -j \left(\frac{50}{75} \right) \cdot \underline{U}_1$$

$$P_{RP2} = \frac{1}{2} \frac{|\underline{U}_2|^2}{Z_{ref2}}$$

$$P_{RP3} = \frac{1}{2} \frac{|\underline{U}_3|^2}{Z_{ref3}}$$

$$\underline{U}_3 = \underline{U}_2$$

$$\frac{P_{RP2}}{P_{RP3}} = \frac{50/\sqrt{2}}{50/\sqrt{2}} = 3$$

LSG. (107)

Das Netzwerk ist reziprok. Daraus folgt: $z_{12} = z_{21}$

1 z_{11} und z_{22} : Spannungsteiler $z_{11} = z_a + z_c // (z_b + z_d)$

$$z_{22} = z_c // (z_b + z_d)$$

$$z_{21} = \frac{U_2}{I_1} \Big|_{I_2=0} = \frac{z_d \cdot I_1''}{I_1' + I_1''} = \frac{z_d \cdot I_1''}{I_1'' + I_1'' \left(\frac{z_b + z_d}{z_c} \right)} = \frac{z_c \cdot z_d}{z_b + z_c + z_d}$$

I_1' = Strom durch z_c

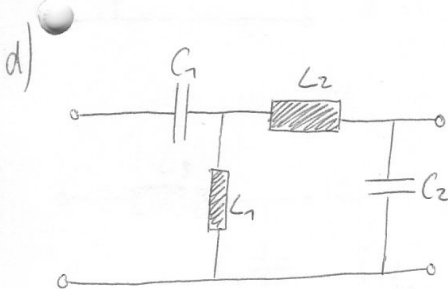
I_1'' = Strom durch z_b und z_d

reziprok $\Rightarrow z_{12} = z_{21}$

$$z_{12} = \frac{1}{z_b + z_c + z_d} \begin{bmatrix} z_a(z_b + z_c + z_d) + z_c(z_b + z_d) & z_c \cdot z_d \\ z_c \cdot z_d & z_d(z_b + z_c) \end{bmatrix}$$

$$c) \quad z_a = -j \frac{1}{\omega_{AP} C_1} + j \frac{\omega_{AP} \cdot 1}{\omega_{AP}^2 \cdot C_1} = 0$$

$$\Rightarrow z_{AP} = \frac{1}{z_b + z_c + z_d} \begin{bmatrix} z_c(z_b + z_d) & z_c \cdot z_d \\ z_c \cdot z_d & z_d(z_b + z_c) \end{bmatrix}$$



$$z_d = -j \frac{1}{\omega C_2} \quad z_c = j \omega L_1$$

$$z_c - z_d = +j \frac{1}{\omega C_2} + j \omega L_1 \Rightarrow \operatorname{Im}\{z_c - z_d\} > 0$$

$$e) \quad z_a = 10 \Omega$$

$$z_{\text{Transistor}} = 1 - j1$$

$$z_a = 0 \quad z_b = j 0.6 \quad z_c = j 0.5 \quad z_d = -j 2$$

$$Z_{in} = Z_c // (Z_s + Z_d // Z_{transistor}) = 0,4 + j0,2$$

$$S_{in} = \frac{0,4 + j0,2 - 1}{0,4 + j0,2 + 1} = -0,4 + j0,2$$

$$Z_{a,ideal} = -j0,2 \Rightarrow Z_{a,ideal} = -j2\Omega$$

$$Z_g = 0,4 \Rightarrow Z_g = 4\Omega = 0,4 Z_o$$

LSR. (407)

$$\underline{S}_{21} = \frac{\underline{b}_2}{\underline{a}_2} = \frac{\underline{b}_2' e^{j\beta l_a}}{\underline{a}_2' e^{j\beta l_e}} = \underline{S}_{21}' \cdot e^{j\beta(l_e + l_a)}$$

$$\underline{S}_{22} = \frac{\underline{b}_2}{\underline{a}_2} = \frac{\underline{b}_2' \cdot e^{j\beta l_a}}{\underline{a}_2' e^{j\beta l_a}} = \underline{S}_{22}' \cdot e^{j2\beta l_a}$$

b)

$$\underline{S}_{11} = \underline{S}_{11}' = 0,72 \angle -43^\circ \quad 1/2 \text{ Transformation}$$

$$\underline{S}_{22} = 0$$

$$\underline{S}_{22} = \underline{S}_{22}' + 90^\circ = 0,55 \angle -114^\circ \quad \text{Drehung um } 1/4 (+90^\circ) \text{ (entgegen dem URS-zeigersinn)}$$

c)

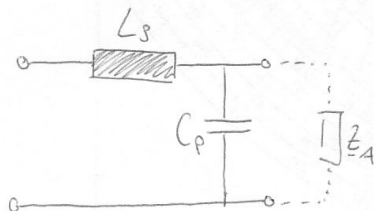
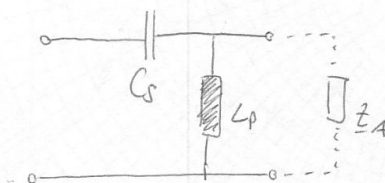
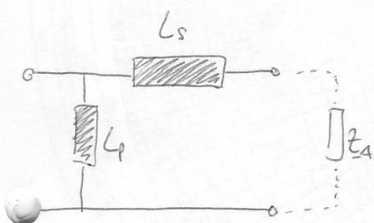
$$\underline{Z}_{11} = 1,1 - j2,1$$

$$R_{gs} = 1,1 \quad \omega C_{gs} = \frac{1}{2,1}$$

$$\underline{Y}_{22} = 0,83 + j1,18$$

$$R_{ds} = \frac{1}{0,83} \quad \omega C_{ds} = 1,18$$

d)



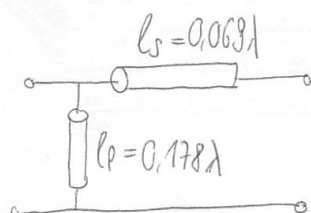
$$\underline{Z}_{Ls} = j1,4$$

$$\underline{Y}_{Cp} = j0,26$$

e)

ohne Eingangs-Anpassung

$$\overline{F} = 1,73 \text{ dB}$$

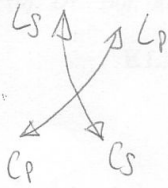


Abschluss der Strahlleitung: short
(verhält sich wie parallele Induktivität)

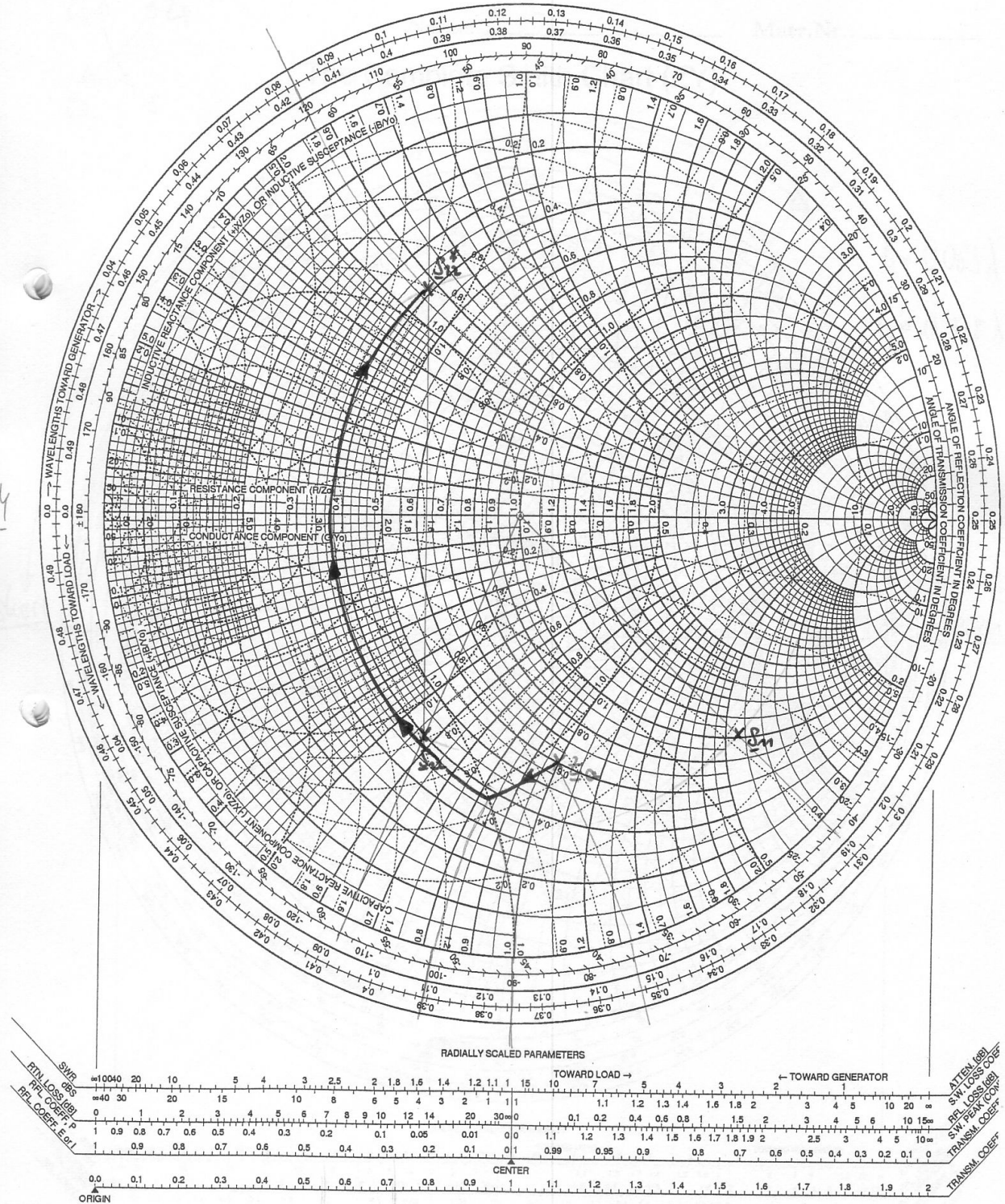
LSA

407

A:8



The Complete Smith Chart (ZY)



KLAUSURAUFGABEN "ELEKTROMAGNETISCHE FELDER 2 (EE)"

Hilfsblatt 3 zu Aufgabe 6, Unterpunkt e)

Name: _____ Matr.Nr.: _____

The Complete Smith Chart (ZY)

