

Aufgabe 1

a)

$$\vec{h} = \omega \sqrt{\epsilon_0 \mu_0} \cdot \vec{e}_z$$

$$\vec{E} = \vec{E}_0 \cdot \exp(-jhz) = E_0 \cdot e^{j\varphi} \cdot e^{-jhz} \cdot \vec{e}_x$$

$$= E_0 \cdot [\cos \varphi + j \sin \varphi] \cdot \vec{e}_x \cdot e^{-jhz}$$

Randbedingungen:

$$\left. \frac{\partial}{\partial z} \right|_{z=0} \{ E_0 \cdot e^{j\varphi} \} = 0 \Rightarrow \varphi = \frac{\pi}{2}, \frac{3\pi}{2}, \frac{5\pi}{2}, \dots$$

$$\Rightarrow \cos \varphi = 0$$

$$e^{j\varphi} = j, \text{ da } \sin \frac{\pi}{2} = 1$$

Wahl von  $\varphi = \frac{\pi}{2}$

$$\Rightarrow \vec{E} = j \cdot E_0 \cdot \vec{e}_x \cdot e^{-jhz}$$

$$! \vec{E} = -E_0 \cdot \vec{e}_x \cdot \sin(\omega t - kz)$$

b)

$$\vec{H} = \frac{1}{Z} \cdot (\vec{e}_z \times \vec{E})$$

da TEM-Welle

$$\Rightarrow \vec{H} = \sqrt{\frac{\epsilon_0}{\mu_0}} \cdot j \cdot E_0 \cdot e^{-jhz} \cdot \vec{e}_y$$

$$\vec{H} = H_0 \{ \vec{H} \cdot e^{+j\omega t} \} = \sqrt{\frac{\epsilon_0}{\mu_0}} \cdot E_0 \cdot \vec{e}_y \cdot H_0 \{ e^{-jhz} \cdot e^{j\omega t} \}$$

$$= \sqrt{\frac{\epsilon_0}{\mu_0}} \cdot E_0 \cdot \vec{e}_y \cdot (-\sin(\omega t - kz))$$

c)

$$\Phi_L(t) = \int \mu_0 \vec{H} d\vec{r}$$

$$d\vec{r} = dx dz \cdot \vec{e}_y$$

$$= \mu_0 \int_a^z \sqrt{\frac{\epsilon_0}{\mu_0}} \cdot E_0 \cdot (-\sin(\omega t - kz)) dz$$

$$= -a \cdot \sqrt{\epsilon_0 \mu_0} \cdot E_0 \cdot \int_{2a}^a \sin(\omega t - kz) dz$$

Substitution:  $u = \omega t - kz$  etc

$$= +a \cdot \sqrt{\epsilon_0 \mu_0} \cdot \frac{1}{\omega \sqrt{\epsilon_0 \mu_0}} \cdot [-\cos(u)]_{\omega t - 2ka}^{\omega t - ka}$$

$$= -\frac{a}{\omega} \cdot [\cos(\omega t - ka) - \cos(\omega t - 2ka)] \cdot E_0$$

$$d) \oint \vec{B}_{\text{ind}} \cdot d\vec{s} = -\dot{\Phi}_L(t)$$

$$= -E_{rr} \cdot \frac{a}{c} \cdot \omega \cdot [\sin(\omega t - 2ka) - \sin(\omega t - ka)]$$

$$= -a \cdot E_{rr} \cdot [\sin(\omega t - 2ka) - \sin(\omega t - ka)]$$

$$e) \vec{E}_{\text{tot}} = -E_{rr} \cdot \vec{e}_x \cdot \sin(\omega t - kz)$$

$$\oint \vec{E} \cdot d\vec{s} = a \cdot (-E_{rr}) \cdot [\sin(\omega t - k \cdot 2a) - \sin(\omega t - k \cdot a)]$$

da das eingetragte E-Feld nur eine x-Komponente hat

Beiträge nur auf

(1)  $\rightarrow$  (2) und (7)  $\rightarrow$  (4)

Math. Drehsinn beachten!

(1)  $\rightarrow$  (2) mit neg. Vorzeichen

Ergebnisse d) und e) müssen gleich sein, da beide aus den Maxwell-Gl. folgen.

f)  $\oint \vec{B}_{\text{ind}} \cdot d\vec{s}$  verschwindet wenn beide sin-Argumente  $n \cdot 2\pi$  Phasendifferenz haben

$$\Rightarrow k \cdot a = n \cdot 2\pi$$

$$\Rightarrow \omega \sqrt{\epsilon_0 \mu_0} \cdot a = n \cdot 2\pi$$

$$\Rightarrow \omega = \frac{n \cdot 2\pi}{a \sqrt{\epsilon_0 \mu_0}} ! \quad n = 1, 2, 3, 4, \dots \quad (n \neq 0, \text{ da } \omega > 0)$$

$$\Rightarrow \lambda = \frac{c}{f} = \frac{c}{\frac{\omega}{2\pi}} = \frac{1}{\frac{1}{2\pi} \cdot \frac{n \cdot 2\pi}{a \sqrt{\epsilon_0 \mu_0}}} = \frac{a \sqrt{\epsilon_0 \mu_0}}{n} = \frac{a}{n}$$

a) linear polarisiert:  $|\vec{k}_e| = \omega \sqrt{\epsilon_0 \mu_0} \rightarrow a = \frac{\omega}{\sqrt{2}} \sqrt{\epsilon_0 \mu_0}$

b) Ansatz 1 (allgemein  $g_u(k, y)$ ):  $\vec{V} \times \vec{H} = j\omega \epsilon \vec{E}$

Ansatz 2 (nur für TEM-Fall  $g_u(k, y)$ ):  $\vec{E} = -\vec{\nabla} \phi = -\vec{\nabla} \left( \frac{m}{k} \times \vec{k} \right)$ ;  $\vec{E} = -\vec{\nabla} \left( \frac{m}{k} \times \vec{k} \right)$ ;  $\vec{E} = -\vec{\nabla} \left( \frac{m}{k} \times \vec{k} \right)$

$$\vec{z}_0 = \sqrt{\frac{\mu_0}{\epsilon_0}}; \quad \vec{n}_r = \frac{1}{\sqrt{2}} \cdot \begin{pmatrix} -1 \\ -1 \\ 0 \end{pmatrix}$$

$$\Rightarrow \vec{E}_e = -\vec{E}_z \frac{j\omega \epsilon_0}{2H_{0r} \cdot a} e^{-j k_{0r} y} = -\vec{E}_z \frac{\omega \epsilon_0}{2H_{0r} \cdot a} e^{-j k_{0r} y} = \vec{E}_z \frac{\omega \epsilon_0}{2H_{0r} \cdot a} e^{-j k_{0r} y}$$

Gesetzt:  $H_m = 0$  und  $E_{0m} = 0 \Rightarrow H_{0r} = \frac{H_{0e}}{\sqrt{2}}$

c) an Grenzfläche ( $x=0$ ) gilt: Halbraum  $\vec{H}_R = \vec{H}_L$

$$\vec{J}_F = \text{Rot} \vec{H} = \vec{e}_x \times \left( \vec{H}_1^{\text{Halbraum 1}} - \vec{H}_2^{\text{Halbraum 2}} \right) = \vec{e}_x \times (-\vec{H}_1^{\text{Halbraum 1}})$$

$$= \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} \frac{H_0}{\sqrt{2}} (e^{-j k_{0r} y} + e^{-j k_{0r} y})$$

$$= \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ -2 \\ 0 \end{pmatrix} \frac{H_0}{\sqrt{2}} e^{-j k_{0r} y} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} \frac{H_0}{\sqrt{2}} e^{-j k_{0r} y}$$

$$\vec{J}_F(x, t) = \vec{J}_F \left\{ \frac{H_0}{\sqrt{2}} \cos(qy - \omega t) \right\}$$

$$d) \quad \underline{\bar{H}} = \underline{\bar{H}}_e + \underline{\bar{H}}_r = \frac{H_0 e}{\sqrt{2}} \begin{pmatrix} e^{-jk_z z} & -e^{-jk_x x} \\ e^{jk_x x} & e^{jk_z z} \end{pmatrix} = \frac{H_0 e}{\sqrt{2}} e^{j\alpha} \begin{pmatrix} -2j \sin(ax) & 2 \cos(ax) \\ 0 & 0 \end{pmatrix}$$

$$\underline{\bar{E}} = \underline{\bar{E}}_e + \underline{\bar{E}}_r = H_0 e \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} + H_0 e \begin{pmatrix} e^{-jk_z z} & e^{-jk_x x} \\ e^{jk_x x} & e^{jk_z z} \end{pmatrix} = H_0 e \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 2j \sin(ax) \end{pmatrix}$$

$$\underline{\bar{E}}_r \times \underline{\bar{H}}_e^* = \frac{H_0 e^2}{\sqrt{2}} \begin{pmatrix} -4j \sin(ax) \cos(ax) \\ -4 \sin^2(ax) \\ 0 \end{pmatrix}$$

$$\frac{1}{2} \operatorname{Re} \{ \underline{\bar{E}} \times \underline{\bar{H}}^* \} = \sqrt{2} \frac{H_0^2 e^2}{2} \begin{pmatrix} 0 \\ -\sin^2(ax) \\ 0 \end{pmatrix}$$

c) Richtung d. Zeitmittels d. Poynting-Vektors:  $(-\underline{e}_y)$   
 Überlagerung ergibt  $\underline{E}_y$ -Welle

Aufgabe 3

$$\begin{cases} \vec{E}_1 = 0 \\ \vec{E}_2 = \vec{f}(x, z) \cdot e^{-j\beta z} \cdot e_x \end{cases} \quad T E_x - \text{Welle}$$

$$\text{mit } \beta^2 = \omega^2 \epsilon_{\text{eff}} \mu_0 \quad \epsilon_2 \leq \epsilon_{\text{eff}} \leq \epsilon_1$$

$$E_x = 0$$

$$\Delta \vec{f}_1 + k_1^2 \vec{f}_1 = 0 \quad \text{Helmholtz-Gleichung}$$

$$\boxed{\vec{f}_1'' + p_1^2 \cdot \vec{f}_1 = 0}$$

$$\text{mit } p_1^2 = k_1^2 - \beta^2 \quad \text{oder } p_1^2 = (\epsilon_1 - \epsilon_{\text{eff}}) \cdot k_0^2$$

$$\text{Mit } \alpha_2^2 = -p_1^2 \text{ folgt:}$$

$$p_1^2 \geq 0 \quad p_2^2 \leq 0 \quad \alpha_2^2 \geq 0$$

$$\boxed{\begin{aligned} \vec{f}_1'' + p_1^2 \cdot \vec{f}_1 &= 0 \\ \vec{f}_2'' - \alpha_2^2 \cdot \vec{f}_2 &= 0 \end{aligned}}$$

$$\vec{f}_1(x) = A_1 \cdot \cos(p_1 x) + B_1 \cdot \sin(p_1 x)$$

$$\vec{f}_2(x) = A_2 \cdot e^{\alpha_2 x} + B_2 \cdot e^{-\alpha_2 x}$$

$$\vec{E}_1 = -\nabla \vec{f}_1 \times \vec{e}_x = \left( 0, -\frac{\partial \vec{f}_1}{\partial z}, 0 \right)$$

$$\vec{H}_1 = \frac{1}{j\omega\mu_0} \left( k_1^2 \vec{f}_1 \cdot \vec{e}_x + \nabla \left( \frac{\partial \vec{f}_1}{\partial x} \right) \right)$$

$$= \left( \frac{1}{j\omega\mu_0} \left( k_1^2 + \frac{\partial^2}{\partial x^2} \right) \vec{f}_1, 0, \frac{1}{j\omega\mu_0} \cdot \frac{\partial \vec{f}_1}{\partial x} \frac{\partial}{\partial z} \right)$$

$$\text{mit } k_1^2 = \omega^2 \epsilon_1 \mu_0 = \epsilon_1 \cdot k_0^2 \quad k_0^2 = \omega^2 \epsilon_0 \mu_0$$

$$E_1 = - \frac{\partial \tilde{f}_1}{\partial z} = j\beta \tilde{f}_1 \cdot e^{-j\beta z}$$

$$E_1 = j\beta \cdot (A_1 \cdot \cos(p_1 x) + B_1 \cdot \sin(p_1 x)) \cdot e^{-j\beta z}$$

$$E_2 = j\beta (A_2 \cdot e^{\alpha_2 x} + B_2 \cdot e^{-\alpha_2 x}) \cdot e^{-j\beta z}$$

$$\tilde{H}_1 = \frac{\beta^2}{j\omega\mu_0} \cdot \tilde{f}_1 = \frac{\beta^2}{j\omega\mu_0} \cdot \tilde{f}_1 \cdot e^{-j\beta z}$$

$$\tilde{H}_1 = \frac{\beta^2}{j\omega\mu_0} (A_1 \cdot \cos(p_1 x) + B_1 \cdot \sin(p_1 x)) \cdot e^{-j\beta z}$$

$$\tilde{H}_2 = \frac{\beta^2}{j\omega\mu_0} (A_2 \cdot e^{\alpha_2 x} + B_2 \cdot e^{-\alpha_2 x}) \cdot e^{-j\beta z}$$

$$\frac{\partial^2 \tilde{f}_1}{\partial z^2} = - \frac{\beta^2}{j\omega\mu_0} \cdot \frac{\partial \tilde{f}_1}{\partial z} \cdot e^{-j\beta z}$$

$$\tilde{H}_1 = \frac{\beta \cdot p_1}{\omega\mu_0} (A_1 \cdot \sin(p_1 x) - B_1 \cdot \cos(p_1 x)) \cdot e^{-j\beta z}$$

$$\tilde{H}_2 = - \frac{\beta \alpha_2}{\omega\mu_0} (A_2 \cdot e^{\alpha_2 x} - B_2 \cdot e^{-\alpha_2 x}) \cdot e^{-j\beta z}$$

$$A_1^2 f_1 + f_1''$$

$$A_2^2 f_1 + (-p_2) f_1'$$

$$(A_1^2 - p_1^2) \cdot f_1$$

$$B_2 \cdot f_1$$

c) elektrische Wand bei  $x=0$ :

$$\rightarrow \tilde{E}_{tan} = 0 \text{ und } \tilde{H}_{norm} = 0 \text{ bzw. } \frac{\partial}{\partial n} \tilde{H}_{tan} = 0$$

$$\boxed{A_1 = 0} \quad \left\{ \begin{array}{l} E_{y1}(x=0) = 0 \\ H_{x1}(x=0) = 0 \\ \frac{\partial H_{z1}}{\partial x}(x=0) = 0 \end{array} \right.$$

Bedingung für  $x \rightarrow \infty$ :

$$\boxed{A_2 = 0} \quad \left\{ \begin{array}{l} E_{y2}(x \rightarrow \infty) = 0 \\ H_{x2}(x \rightarrow \infty) = 0 \\ H_{z2}(x \rightarrow \infty) = 0 \end{array} \right.$$

a) Grenzfläche zweier Dielektrika bei  $x=0$ :  
 $\vec{E}_{\text{tan}}$  stetig und  $\vec{H}_{\text{tan}}$  stetig

$$E_{y1}(x=0) = E_{y2}(x=0)$$

$$H_{z1}(x=0) = H_{z2}(x=0)$$

$$B_1 \cdot \sin(p_1 h) = B_2 \cdot e^{-\alpha_2 h}$$

$$-p_1 B_1 \cos(p_1 h) = \alpha_2 \cdot B_2 \cdot e^{-\alpha_2 h}$$

$$\Rightarrow \tan(p_1 h) = -\frac{p_1}{\alpha_2}$$

charakteristische Gleichung

$$\text{e) } \tan(p_1 h) = -\sqrt{3} \quad \tan\left(\frac{\pi}{3}\right) = \sqrt{3}$$

$$\Rightarrow p_1 h = \pi - \frac{\pi}{3} = \frac{2\pi}{3}$$

kleinster Eigenwert  $p_1$

$$\Rightarrow p_1 = \frac{2\pi}{3h} \quad \text{und} \quad \alpha_2 = \frac{p_1}{\sqrt{3}} = \frac{2\pi}{3\sqrt{3} \cdot h}$$

charakteristische Gleichung

$$p_2^2 = k_1^2 - \beta^2 = \epsilon_2^2 \mu_0 (\epsilon_1 - \epsilon_2) \geq 0$$

$$\alpha_2^2 = \beta^2 - k_1^2 = \epsilon_2^2 \mu_0 (\epsilon_2 - \epsilon_1) \geq 0$$

$$\Rightarrow p_2^2 + \alpha_2^2 = \epsilon_2^2 \mu_0 (\epsilon_1 - \epsilon_2)$$

$$\Rightarrow \boxed{\omega^2 = \frac{p_1^2 + \alpha_2^2}{\mu_0 (\epsilon_1 - \epsilon_2)}}$$



$$\Rightarrow \alpha_2^2 - p_1^2 = \omega^2 \mu_0 (2\epsilon_{eff} - \epsilon_1 - \epsilon_2)$$

$$\Rightarrow \epsilon_{eff} = \frac{\alpha_2^2 - p_1^2}{2\omega^2 \mu_0} + \frac{\epsilon_1 + \epsilon_2}{2}$$

$\omega^2$  einsetzen:

$$\epsilon_{eff} = \frac{\alpha_2^2 - p_1^2}{\alpha_2^2 + p_1^2} \cdot \frac{\epsilon_1 - \epsilon_2}{\epsilon_1 + \epsilon_2} + \frac{\epsilon_1 + \epsilon_2}{2}$$

$$\Rightarrow \boxed{\epsilon_2 \leq \epsilon_{eff} \leq \epsilon_1}$$

$$\omega^2 = \frac{4\pi^2}{94^2} \left(1 + \frac{1}{3}\right) \cdot \frac{\mu_0(\epsilon_1 - \epsilon_2)}{1}$$

$$\omega^2 = \frac{16\pi^2}{224^2} \cdot \frac{\mu_0(\epsilon_1 - \epsilon_2)}{1}$$

$$\epsilon_{eff} = \frac{1/3 - 1}{1/3 + 1} \cdot \frac{\epsilon_1 - \epsilon_2}{\epsilon_1 + \epsilon_2} + \frac{\epsilon_1 + \epsilon_2}{2}$$

$$\Rightarrow \boxed{\epsilon_{eff} = \frac{\epsilon_1 + 3\epsilon_2}{4} = \epsilon_2 + \frac{1}{4}(\epsilon_1 - \epsilon_2)}$$

f) Grenzfrequenz für  $\alpha_2 = 0$  bzw.  $\epsilon_{eff} = \epsilon_2$   
 (Felder liegen in x-Richtung nicht mehr ab)  
 $\Rightarrow \tan(p_1 h) = -\infty$  charakt. Gleichung.

$$\Rightarrow p_1 \cdot h = \frac{\pi}{2}$$

$\downarrow$  kleinste Eigenwert  $= 1$

$$\Rightarrow n_1 = \frac{2h}{\lambda} \quad \Rightarrow \epsilon_{eff} = -\frac{2}{\epsilon_1 - \epsilon_2} + \frac{2}{\epsilon_1 + \epsilon_2} = \epsilon_2$$

$$\Rightarrow \cos^2 = \frac{4h^2}{\pi^2} \cdot \frac{\mu_0(\epsilon_1 - \epsilon_2)}{1}$$

$$\Rightarrow \cos = \frac{2h}{\pi} \cdot \frac{\sqrt{\mu_0(\epsilon_1 - \epsilon_2)}}{1}$$

$$\Rightarrow \boxed{f_c = \frac{1}{4h} \cdot \frac{\sqrt{\mu_0(\epsilon_1 - \epsilon_2)}}{1}}$$



a)  $\lambda_2 = 10 \text{ m}$  ;  $\epsilon_r = 4$  ;  $\omega = 2\pi \cdot 10^7 \frac{1}{s}$

elekt. Länge  $\lambda_z = \lambda \cdot f = \frac{c}{\lambda_z} \cdot \frac{1}{\omega} = \frac{c}{\lambda_z} \cdot \frac{1}{2\pi}$

$= \frac{3 \cdot 10^8 \frac{m}{s}}{2 \cdot 10^7 \frac{1}{s}} \cdot \lambda \cdot \frac{1}{4} = \frac{3}{2} \lambda \approx 1$

$\vec{v} = \vec{e}_z \cdot \frac{\lambda}{2\pi}$

b)  $\vec{E}(s, \varphi, z) = \vec{E}_A(s, \varphi) \cdot e^{-j k_z \cdot z} = \vec{E}_L(s, \varphi) \cdot e^{-j \frac{\omega}{c} \cdot z} = \vec{E}_L(s, \varphi) \cdot e^{-j \frac{2\pi}{\lambda} \cdot z}$

c)  $= \vec{E}_L(s, \varphi) \cdot e^{-j \frac{\omega}{c} \cdot z} = \vec{E}_L(s, \varphi) \cdot e^{-j \frac{2\pi}{\lambda} \cdot z}$

d)  $\Delta^2 \Phi(s, \varphi, z=0, t) = 0 \Rightarrow \frac{1}{s} \cdot \frac{\partial}{\partial s} \left( s \frac{\partial \Phi}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 \Phi}{\partial \varphi^2} = 0$   
 (wegen TM-Wellen (potentiell/ungekoppelt))

Ausatz  $\Phi(s, \varphi, z=0, t) = \text{const}_1 + \text{const}_2 \cdot \ln(s) \cdot h(\varphi)$   
 ist Lsg. der DGL

e)  $\vec{E}_A(s, \varphi)$  gegeben

$\Phi(s, \varphi, z=0, t) = \text{const}_2 \cdot \ln(s) \cdot h(\varphi) + \text{const}_1$

Es gilt  $h(\varphi) = 0$

$\Phi(s=0, \varphi, z=0, t) - \Phi(s=r_a, \varphi, z=0, t) = U_0 \cdot s_0(\varphi, t)$   
 $\text{Re} \left\{ \vec{E}_A(s, \varphi) \cdot e^{j\omega t} \right\} = -\nabla^2 \Phi(s, \varphi, z=0, t)$

$$(*) \text{ const}_2 \cdot h\left(\frac{\pi}{\tau}\right) \cdot h(t) = u_0 \sin(\omega t)$$

$$\Rightarrow \text{const}_2 = \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \quad \text{und} \quad h(t) = \sin(\omega t)$$

$$\Rightarrow \Phi = - \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \cdot h(\vartheta) \cdot \sin(\omega t)$$

$$\begin{aligned} \text{Re}\{\underline{\tilde{E}}_A(\vartheta, t) \cdot e^{j\omega t}\} &= - \frac{\partial \Phi}{\partial \vartheta} \cdot \underline{e}_\vartheta = \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \cdot \frac{1}{\vartheta} \cdot \underline{e}_\vartheta \sin(\omega t) \\ \Rightarrow \underline{\tilde{E}}_A(\vartheta, t) &= -j \cdot \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \cdot \frac{1}{\vartheta} \cdot \underline{e}_\vartheta \end{aligned}$$

$$\underline{\tilde{E}}_L = \underline{\tilde{E}}_A \cdot e^{-j \frac{\vartheta}{\tau} \cdot z}$$

$$f) \quad k_z = 1 \cdot m; \quad \omega = 2\pi \cdot 10^5 \frac{1}{s}$$

$$\frac{k_z}{\lambda} = \frac{k_z}{\omega} \cdot \frac{\omega}{2\pi} = \frac{1 \cdot m}{3 \cdot 10^8 \frac{m}{s}} \cdot 2 \cdot 10^5 s^{-1} = \frac{2}{3} \cdot 10^{-3} < 1$$

$$\underline{\tilde{E}}(g, \varphi, z, t) = \text{Re}\{\underline{\tilde{E}} \cdot e^{j\omega t}\}$$

$$= \text{Re}\left\{-j \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \cdot \frac{1}{\vartheta} \cdot \underline{e}_\vartheta \cdot e^{-j k_z z + j \omega t}\right\}$$

$$= \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \cdot \frac{1}{\vartheta} \cdot \underline{e}_\vartheta \cdot \text{Re}\left\{-j \left(\cos(\omega t - k_z z) + j \sin(\omega t - k_z z)\right)\right\}$$

$$= \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \cdot \frac{1}{\vartheta} \cdot \underline{e}_\vartheta \cdot \sin(\omega t - k_z z) \quad \text{da} \quad \frac{k_z}{\lambda} < 1$$

$$\approx \frac{u_0}{h\left(\frac{\pi}{\tau}\right)} \cdot \frac{1}{\vartheta} \cdot \underline{e}_\vartheta \cdot \sin(\omega t)$$

Aufgabe 2

a)  $\vec{E}(z) = \frac{U_0}{h} \cdot \exp(-jhz) \cdot \vec{e}_x$ ,  $h = \omega \sqrt{\epsilon \mu}$

$\vec{H}(z) = \frac{1}{Z_f} \cdot (\vec{n} \times \vec{E}) = \sqrt{\frac{\mu}{\epsilon}} \cdot (\vec{n} \times \vec{E})$   
 $= \sqrt{\frac{\mu}{\epsilon}} \cdot (e_z \times \vec{e}_x) \cdot \frac{U_0}{h} \cdot e^{-jhz}$   
 $= \sqrt{\frac{\mu}{\epsilon}} \cdot \frac{U_0}{h} \cdot e^{-jhz} \cdot \frac{\partial}{\partial y}$

b)  $U_1(z) = \int_0^z \vec{E}(z) dz = U_1(z) \Rightarrow U_1(z) = U_0 \cdot e^{-jhz}$

$U_1(z) = \oint \vec{H} \cdot d\vec{l} = \oint \vec{H} \cdot \vec{e}_y \cdot dz = \oint H_y \cdot dz$

$\Rightarrow \oint H_y \cdot dz = \oint \frac{U_0}{h} \cdot e^{-jhz} \cdot \frac{1}{3} \cdot 9 = \frac{U_0}{h} \cdot e^{-jhz} \cdot 3$

$Z_1 = \frac{U_1}{I_1} = \frac{9}{4} \cdot \sqrt{\frac{\mu}{\epsilon}} = Z_f \cdot \frac{3}{4}$

c)  $\vec{Z} = 0: U_1 + U_2 = U_1 + U_2$

$\Rightarrow -\frac{Z_1}{U_1} + \frac{Z_1}{U_2} = \frac{Z_1}{U_1} + \frac{Z_1}{U_2} \Rightarrow -\frac{Z_1}{U_1} + \frac{Z_1}{U_2} = \frac{Z_1}{U_1} + \frac{Z_1}{U_2}$

$\vec{Z} = Z: U_1 \cdot e^{-jhz} = -U_2 \cdot e^{-jhz}$

③

Einschub (nicht zuzuordnen):

$e^{-j\frac{\pi}{2}} = e^{-j\frac{\pi}{2}} = \cos(\frac{\pi}{2}) - j \sin(\frac{\pi}{2}) = -j$   
 $e^{j\frac{\pi}{2}} = j$

$$= -j \frac{U_0}{2Z_L} - j \frac{U_0}{2Z_L} = -j \frac{U_0}{Z_L}$$

$$U_1 = \left. \frac{U_2}{Z_L} \right|_{Z=0} = j \frac{U_0}{Z_L} \cdot e^{-j\beta x} + \frac{U_0}{2Z_L} \cdot e^{-j\beta x} = \frac{U_0}{Z_L} \cdot e^{-j\beta x}$$

$$\left. \frac{U_2}{Z_L} \right|_{Z=0} = 0, \text{ da } \frac{U_2}{Z_L} = \frac{U_0}{Z_L} + \frac{U_0}{Z_L}$$

$$U_1 = \frac{U_0}{Z_L} = \frac{U_0}{Z_L}$$

$$\left. \frac{U_2}{Z_L} \right|_{Z=0} = \frac{U_0}{Z_L} - \frac{U_0}{Z_L} = 0$$

$$\frac{Z}{\lambda} \approx 1$$

$$\text{mit (7) folgt: } \overline{Z} = Z_L$$

$$\Rightarrow U_0 = \frac{2U_1}{Z_L} \cdot Z_L$$

$$\Rightarrow \frac{U_0}{Z_L} = \frac{U_1}{Z_L} - \frac{U_2}{Z_L} + \frac{U_2}{Z_L} + \frac{U_2}{Z_L}$$

$$\textcircled{2} \quad \frac{U_1}{Z_L} - \frac{U_0}{Z_L} = \frac{U_2}{Z_L} = \frac{U_2}{Z_L} + \frac{U_2}{Z_L}$$

$$\textcircled{3} + \textcircled{4} \quad U_1 + U_2 = U_0 \Rightarrow U_1 = U_0 - U_2$$

$$\Rightarrow U_1 \cdot (-1) = -U_2 \Rightarrow U_1 = U_2$$

$$\textcircled{2} \quad \frac{U_1}{Z_L} - \frac{U_2}{Z_L} = \frac{U_2}{Z_L} + \frac{U_2}{Z_L}$$

$$\textcircled{1} \quad U_1 + U_2 = U_0$$

$$d) \lim_{\frac{Z}{\lambda} = 0} U_1 = 0$$

$$\frac{Z}{240} = \sqrt{n}$$

$$\frac{Z}{240} = \sqrt{n} \quad (Z=0)$$

e)  $\sqrt{n} = 0$  (unmöglich)

a) TE<sub>y</sub> - H<sub>y</sub> bündel

(E<sub>x</sub> = 0)

$$\vec{E} = \vec{f}_1(x, z) e^{-j\beta z} = \vec{f}_1(x, z) \cdot e^{-j\beta z}$$

z = 1.2

$\vec{G} = 0 \Rightarrow \vec{E}_x = 0$

mit  $\beta^2 = \omega^2 \epsilon_{eff}(\omega) \mu_0$

$k_z^2 = \omega^2 \epsilon_1 \mu_0$

Helmholtz-Gly:

$$\left( \frac{d^2}{dz^2} + k_z^2 - \beta^2 \right) \vec{f}_1(x) = 0$$

$$\left( \frac{d^2}{dz^2} + k_z^2 \right) \vec{f}_1(x) = 0$$

mit  $k_z^2 = k_1^2 - \beta^2$

~~$$\vec{f}_1(x) = \vec{A}_1 \cos(k_{x1} x) + \vec{B}_1 \sin(k_{x1} x)$$~~

~~$$\vec{f}_2(x) = \vec{A}_2 \cos(k_{x2} x) + \vec{B}_2 \sin(k_{x2} x)$$~~

b) Gebiet ②:

Randbed:  $\vec{E}_{tan} = 0$  und  $\vec{H}_n = 0$

$\vec{E}_{x1}(y=0) = 0$  ✓

$\vec{E}_{z1}(y=0) = 0$  ✓

$\vec{H}_{y1}(y=0) = 0$  ✓

$\vec{H}_{y1}(y=b) = 0$  ✓

$\vec{E}_{y1}(x=0) = 0 \Rightarrow \boxed{\vec{A}_1 = 0}$

$\vec{E}_{z1}(x=0) = 0$  ✓

$\vec{H}_{x1}(x=0) = 0 \Rightarrow \vec{A}_1 = 0$  ✓

Gebiet ②

Randbed:  $\bar{E}_{x2} = 0$  u.  $\bar{H}_{y2} = 0$ 

$$\bar{E}_{x2}(y=0) = 0 \quad \checkmark \quad \bar{E}_{x2}(y=b) = 0 \quad \checkmark$$

$$\bar{E}_{z2}(y=0) = 0 \quad \checkmark \quad \bar{E}_{z2}(y=b) = 0 \quad \checkmark$$

$$\bar{H}_{y2}(y=0) = 0 \quad \checkmark \quad \bar{H}_{y2}(y=b) = 0 \quad \checkmark$$

$$\bar{E}_{y2}(x=2a) = 0 \Rightarrow \boxed{\bar{A}_2 = 0}$$

$$\bar{E}_{z2}(x=2a) = 0 \quad \checkmark$$

$$\bar{H}_{x2}(x=2a) = 0 \Rightarrow \bar{A}_2 = 0 \quad \checkmark$$

Gebiet ①:

$$\bar{E}_{x1} \equiv 0 \quad \text{da} \quad \bar{g}_1 \equiv 0$$

$$\bar{E}_{y1} = -\frac{\partial \bar{A}_1}{\partial x} = j\beta \bar{f}_1$$

$$\bar{E}_{y1} = j\beta (\bar{g}_1 \sin(\beta x)) e^{-j\beta z}$$

$$\bar{E}_{z1} = \frac{\partial \bar{A}_1}{\partial y} \equiv 0 \quad \text{da} \quad \bar{f}_1(x,z)$$

$$\bar{H}_{x1} = \frac{j\omega \mu_0}{\beta^2} \bar{f}_1$$

$$\bar{H}_{x1} = \frac{j\omega \mu_0}{\beta^2} (\bar{g}_1 \sin(\beta x)) e^{-j\beta z}$$

$$\bar{H}_{y1} = \frac{j\omega \mu_0}{\beta^2} \frac{\partial \bar{A}_1}{\partial x} \equiv 0 \quad \text{da} \quad \bar{f}_1(x,z)$$

$$\bar{H}_{z1} = \frac{j\omega \mu_0}{\beta} \frac{\partial \bar{A}_1}{\partial z} = -\frac{j\omega \mu_0}{\beta} \frac{\partial \bar{f}_1}{\partial z}$$

$$\bar{H}_{z1} = -\frac{j\omega \mu_0}{\beta} \bar{g}_1 \cos(\beta x) e^{-j\beta z}$$



Ges: ②:

$$E_{x2} = 0$$

$$E_{y2} = j\beta (\bar{B}_2 \sin(k_{x2}(2d-x))) e^{-j\beta z}$$

$$E_{z2} = 0$$

$$H_{x2} = \frac{\beta^2}{j\omega\mu_0} (\bar{B}_2 \sin(k_{x2}(2d-x))) e^{-j\beta z}$$

$$H_{y2} = 0$$

$$H_{z2} = - \frac{\beta k_{x2}}{\omega\mu_0} \left( -\bar{B}_2 \cos(k_{x2}(2d-x)) \right) e^{-j\beta z}$$

c) Stehigkeit bei  $x=d$   $\bar{E}_{\tan} = \bar{E}_{\tan}$  und  $\bar{H}_{\tan} = \bar{H}_{\tan}$

$$\bar{E}_{y2}(x=d) = \bar{E}_{y2}(x=d)$$

$$\Rightarrow \bar{B}_2 \sin(k_{x2}d) = \bar{B}_2 \sin(k_{x2}d)$$

$$\bar{E}_{z2}(x=d) = \bar{E}_{z2}(x=d) \equiv 0$$

$$\bar{H}_{y2}(x=d) = \bar{H}_{y2}(x=0) \equiv 0$$

$$\bar{H}_{z2}(x=d) = \bar{H}_{z2}(x=d)$$

$$\Rightarrow -k_{x2} \bar{B}_2 \cos(k_{x2}d) = k_{x2} \bar{B}_2 \cos(k_{x2}d)$$

oder

$$\boxed{\bar{H}_{x2} \cot(k_{x2}d) = -\bar{H}_{x2} \cot(k_{x2}d)}$$

$$k_{x2}^2 = k_{x2}^2 - \beta^2$$

oder

$$k_{x2} \tan(k_{x2}d) = -k_{x2} \tan(k_{x2}d)$$

$$k_{x2}^2 = k_{x2}^2 - \beta^2$$

all Fall:  $\epsilon_1 = \epsilon_2$  !  $k_1 = k_2$  !  $k_1 = k_2 \neq 0$

char. Gl.:

$$k_{x1} \cot(k_{x1} \cdot a) = -\widetilde{k_{x2}} \cot(\widetilde{k_{x2}} \cdot a) = -k_{x2}$$

$$\Rightarrow k_{x1} \cot(k_{x1} \cdot a) = 0$$

$$\Rightarrow \cot(k_{x1} \cdot a) = 0 \quad \text{da } k_{x1} \neq 0 \quad (\text{Aufst. Stellung})$$

$$\Rightarrow k_{x1} = \pm \left( \frac{\pi}{2a} \right) ! \pm \frac{3\pi}{2a} ! \pm \frac{5\pi}{2a} ! \dots$$

die andere char. Gl.:

$$k_{x2} \cdot \tan(k_{x1} \cdot a) = -k_{x1} \tan(k_{x2} \cdot a)$$

$$\Rightarrow \tan(k_{x1} \cdot a) = 0 \quad (\text{analog wie oben})$$

$$\Rightarrow k_{x1} = 0 ! \pm \frac{\pi}{a} ! \pm \frac{2\pi}{a} ! \pm \frac{3\pi}{a} ! \dots$$

für  $TE$  - Grundwelle:

( $TE_{x_{n0}}$ -Welle)

$$k_{x1} = k_{x2} = \frac{\pi}{2a}$$

Grenzfrequenz  $\omega_c$  mit  $\beta(\omega_c) = 0$ :

$$k_{x1}^2 = k_1^2 - \beta^2 = k_2^2 = \omega_c^2 \epsilon_1 \mu_0$$

$$\omega_c = \frac{1}{\sqrt{\epsilon_1 \mu_0}} \frac{\pi}{2a}$$

a)  $\text{rot } \vec{H} = j\omega \vec{D} = j\omega \epsilon_0 \vec{E} \Rightarrow \vec{E} = -\frac{1}{j\omega \epsilon_0} \text{rot } \vec{H}$

$\vec{E}_z = -\frac{1}{j\omega \epsilon_0} \left( -\frac{\partial H_y}{\partial z} \vec{e}_z + \frac{\partial H_x}{\partial z} \vec{e}_z \right)$

$\vec{E}_z = -\frac{1}{j\omega \epsilon_0} \left( H_x(x) j\omega \mu_{eff} \epsilon_0 \exp(-j\omega \mu_{eff} z) \vec{e}_z + \frac{dH_x(x)}{dz} \exp(-j\omega \mu_{eff} z) \vec{e}_z \right)$

$\vec{E}_z = -\frac{1}{j\omega \epsilon_0} \left( H_z(x) j\omega \mu_{eff} \epsilon_0 \exp(-j\omega \mu_{eff} z) \vec{e}_z + \frac{dH_z(x)}{dz} \exp(-j\omega \mu_{eff} z) \vec{e}_z \right)$

b) G.B. ~~was~~ für  $\vec{E}$  bei  $x=0$  und  $x=2d$

$\text{rot } \vec{E} = 0 \Rightarrow E_{tan} = 0 \Rightarrow E_z = 0$

$\Rightarrow \frac{dH_x(0)}{dz} = 0$

und  $\frac{dH_z(2d)}{dz} = 0$

(2)

(1)

c) Aufstellen d. Helmholtz-Gl. für G1 und G2

G1:  $\Delta \vec{H} + \omega^2 \mu_0 \epsilon_0 \vec{H} = 0$

G2:  $\Delta \vec{H} + \omega^2 \mu_2 \epsilon_0 \vec{H} = 0$

$\frac{d^2 H_x(x)}{dx^2} - \omega^2 \mu_{eff} \epsilon_0 H_x(x) + \omega^2 \mu_2 \epsilon_0 H_x(x) = 0$

$\frac{d^2 H_z(x)}{dx^2} + \omega^2 \epsilon_0 (\mu_2 - \mu_{eff}) H_z(x) = 0$

$\frac{d^2 H_x(x)}{dx^2} - \omega^2 \mu_{eff} \epsilon_0 H_x(x) + \omega^2 \mu_2 \epsilon_0 H_x(x) = 0$

$\frac{d^2 H_z(x)}{dx^2} + \omega^2 \epsilon_0 (\mu_2 - \mu_{eff}) H_z(x) = 0$

LS:

$H_x(x) = A_1 \cos(p_1 x) + B_1 \sin(p_1 x)$

mit (1)  $\Rightarrow B_1 = 0$

$\Rightarrow H_x(x) = A_1 \cos(p_1 x)$

$H_z(x) = A_2 \cos(p_2(x-2d)) + B_2 \sin(p_2(x-2d))$

mit (2)  $\Rightarrow B_2 = 0$

$\Rightarrow H_z(x) = A_2 \cos(p_2(x-2d))$

d) G.B. in der  $(x=d)$  Ebene

$$\text{Rot } \vec{H} = \vec{0} \text{ und } \text{Rot } \vec{E} = \vec{0}$$

$$\text{Rot } \vec{E} = 0 \rightarrow -\lambda_1 p_1 \sin(p_1 d) = \lambda_2 p_2 \sin(p_2 d)$$

$$\text{Rot } \vec{H} = 0 \Rightarrow \lambda_1 \cos(p_1 d) = \lambda_2 \cos(p_2 d)$$

$$\Rightarrow -p_1 \tan(p_1 d) = p_2 \tan(p_2 d)$$

e) mit  $\omega \rightarrow 0 \Rightarrow |p_1| d \ll 1$  u.  $|p_2| d \ll 1$  gilt:  $\tan(p_1 d) \approx p_1 d$

und  $\tan(p_2 d) \approx p_2 d$

$$-p_1^2 = p_2^2$$

$$-\omega^2 (p_1 - p_2) \epsilon_0 = \omega^2 (p_2 - p_1) \epsilon_0$$

$$-p_1 + p_2 = p_2 - p_1 \Rightarrow p_1 = p_2$$

Phasen Geschw v:

$$\omega \sqrt{\mu_0 \epsilon_0} = \frac{\lambda}{2\pi} = k = \frac{v}{\omega} \Rightarrow v = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\frac{\sqrt{\mu_0 \epsilon_0}}{\sqrt{2}} =$$

$$f(\omega) \neq$$