

zur letzten KGÜ:

$$\Delta \underline{H} := \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) H$$

$$\Delta \underline{\vec{H}} = \frac{\partial^2}{\partial x^2} \underline{\vec{H}} + \frac{\partial^2}{\partial y^2} \underline{\vec{H}} + \frac{\partial^2}{\partial z^2} \underline{\vec{H}}$$

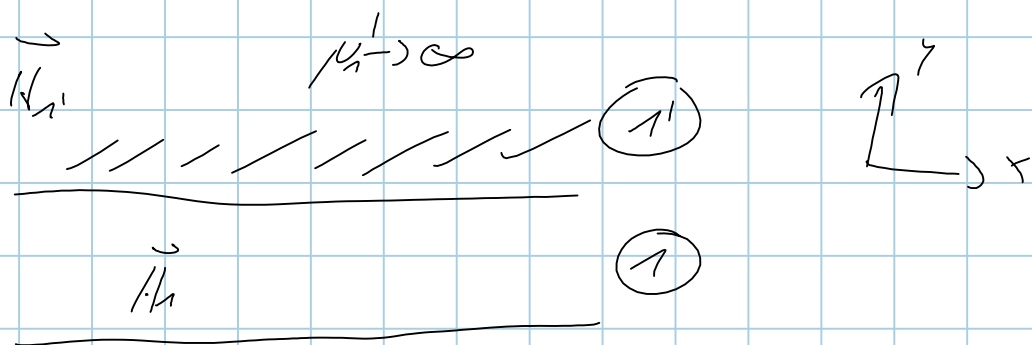
$$\boxed{(\vec{\nabla} \vec{\nabla}) \underline{\vec{H}} \neq \vec{\nabla} (\vec{\nabla} H)}$$

$$(\vec{a} \vec{b}) \vec{c} \neq \vec{a} (\vec{b} \vec{c})$$

$$a(bc) = (ab)c$$

$$\Delta \underline{\vec{H}} = \Delta H_x \vec{e}_x + \Delta H_y \vec{e}_y + \Delta H_z \vec{e}_z$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right)$$

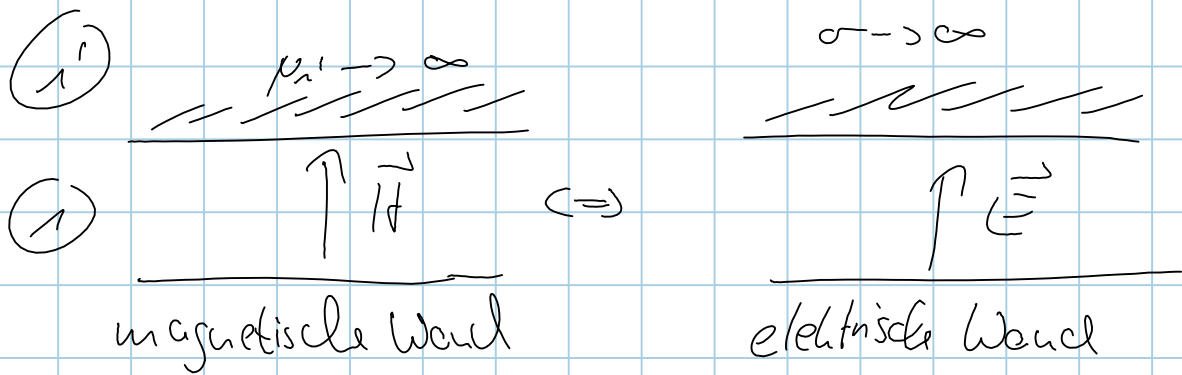
H2000 A.4 Begründung für $\underline{H} = \vec{e}_y \cdot H_y(x)$ 

$$B_{1y} = B_{2y}$$

an Grenzfläche

$$\mu_1 H_{1y} = \mu_2 H_{2y}$$

$$\Rightarrow H_{1y} = \underbrace{\frac{\mu_2}{\mu_1}}_{\rightarrow \infty} H_{2y}$$



$$H_t = 0$$

$$a) \Delta \vec{H} - k^2 \vec{H} = 0 \quad \vec{H} = \vec{e}_y H_y(x)$$

$$\begin{aligned}
 \text{rot } \vec{H} &= \vec{J} + \vec{D} & \text{rot } (\vec{H}) &= \vec{B} & \text{rot } \vec{E} &= -\vec{B} \\
 \Rightarrow \Delta \vec{H} &= \text{rot}(\vec{J}) + j\omega \text{rot}(\epsilon \vec{E}) & & & &= -j\omega \mu \vec{H} \\
 &= \text{rot } \vec{J} + j\omega \epsilon \text{rot}(\vec{E}) & & & & \\
 &= \text{rot } \vec{J} + j\omega \epsilon (-j\omega \mu \vec{H}) & & & & \\
 &= \text{rot } \vec{J} + \omega^2 \epsilon \mu \vec{H} & & & &
 \end{aligned}$$

$$a) \text{rot } \vec{H} = (\sigma_0 + j\omega \epsilon) \vec{E} = \left(1 + j\omega \frac{\epsilon_0}{\sigma_0} \right) \sigma_0 \vec{E}$$

≈ 0

$$\Rightarrow \text{rot rot } \vec{H} = \sigma_0 \cdot \text{rot } \vec{E} = -j\omega \mu_0 \sigma_0 \vec{H} = \underbrace{\text{grad div } \vec{H}}_{=0} - \Delta \vec{H}$$

$$\Rightarrow \Delta \vec{H} - k^2 \vec{H} = 0 \quad k^2 = j\omega \mu_0 \sigma_0$$

$$\vec{H} = H_y(x) \vec{e}_y$$

$$\Rightarrow \frac{d^2}{dx^2} H_y(x) - k^2 H_y(x) = 0$$

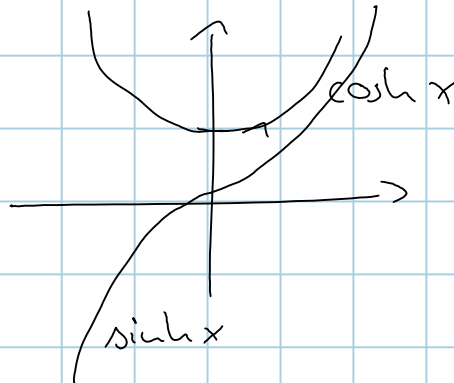
$$H_y(x) = e^{+kx} + e^{-kx}$$

Allg. Lösung: $H_y(x) = \underline{\alpha}' e^{+\underline{k}x} + \underline{\beta}' e^{-\underline{k}x}$

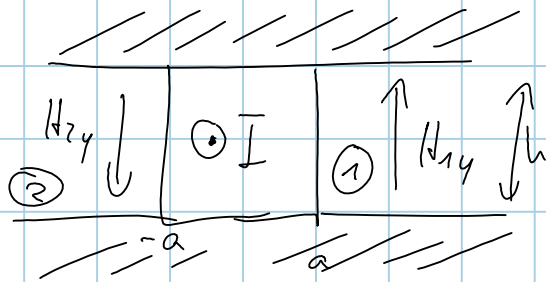
$$H_y(x) = \underline{\alpha} \cosh(\underline{k}x) + \underline{\beta} \sinh(\underline{k}x)$$

$$\left[\cosh x = \frac{e^x + e^{-x}}{2} \right]$$

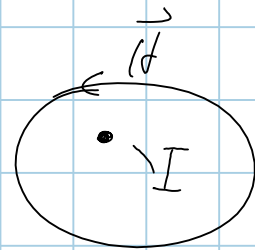
$$x \rightarrow x+a$$



b)



Analogie



$$\oint \underline{H} d\vec{s} = \int \underline{J} d\vec{F}$$

$$\int_0^a H_{1y}(x_1) d\vec{s} + \int_a^0 H_{2y}(x_2) d\vec{s} = \bar{I}$$

$$h \cdot H_{1y}(x_1) + (-H_{2y}(x_2)) = \bar{I}$$

$$2h H_{1y}(x_1) = \bar{I} \Rightarrow H_{1y} = \frac{\bar{I}}{2h}$$

$$H_{2y} = -\frac{\bar{I}}{2h}$$

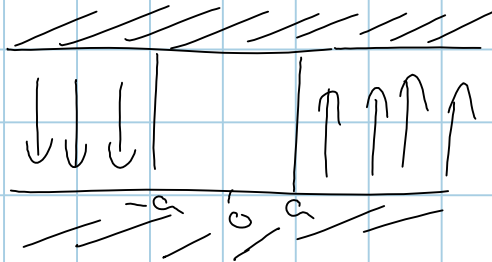
c) $H_y(x) = \underline{\alpha} \cosh(\underline{k}x) + \underline{\beta} \sinh(\underline{k}x)$
(x im Leiter)

$$\underline{H}_y(x) = \frac{\bar{I}}{2h} \quad (\text{für } x > a)$$

$$H_y(x) = -\frac{I}{2L} \quad (\text{für } x < -a)$$

$$\Rightarrow \text{für } x=a: H_y(a) = \alpha \cosh(ka) + \beta \sinh(ka) = \frac{I}{2L}$$

$$\text{" } x=-a: H_y(-a) = \alpha \cosh(-ka) + \beta \sinh(-ka) = -\frac{I}{2L}$$



$$\Rightarrow \alpha = 0 \quad \text{wg. } \cosh(x) = \frac{e^x + e^{-x}}{2}$$

$$\Rightarrow \beta = \frac{I}{2L} \frac{1}{\sinh(ka)}$$

$$\Rightarrow H_y(x) = \frac{I}{2L} \frac{\sinh(kx)}{\sinh(ka)}$$

$$\vec{j} = \vec{e}_z \frac{\partial H_y(x)}{\partial x} = \frac{I}{2L} k \frac{\cosh(kx)}{\cosh(ka)}$$

